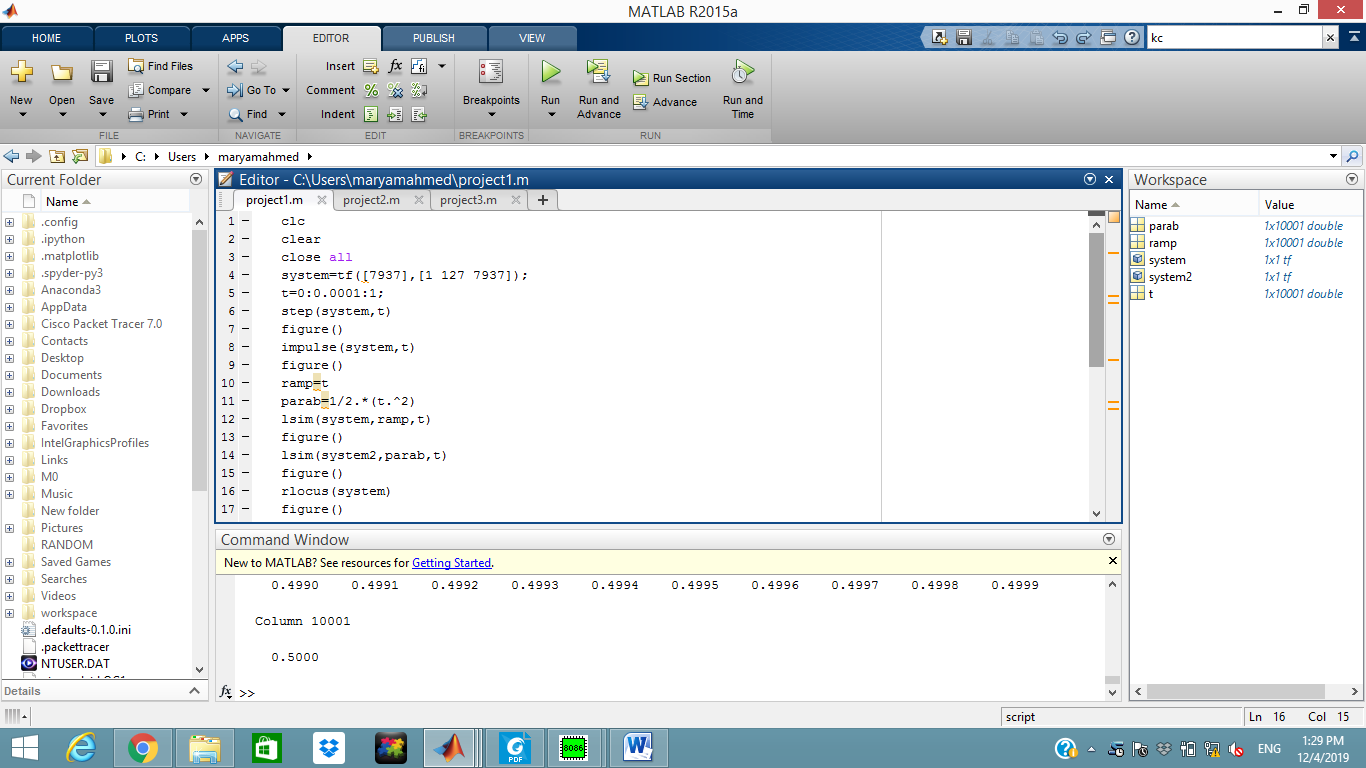
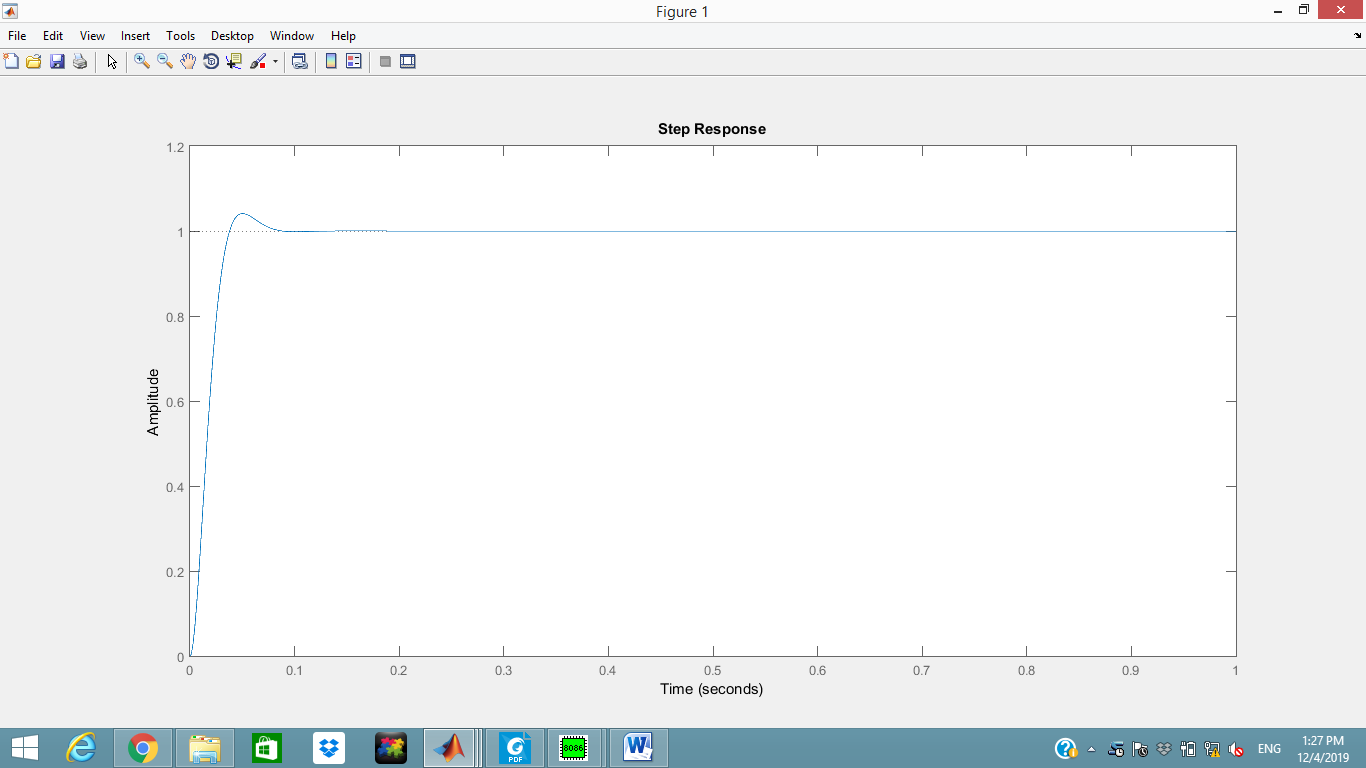
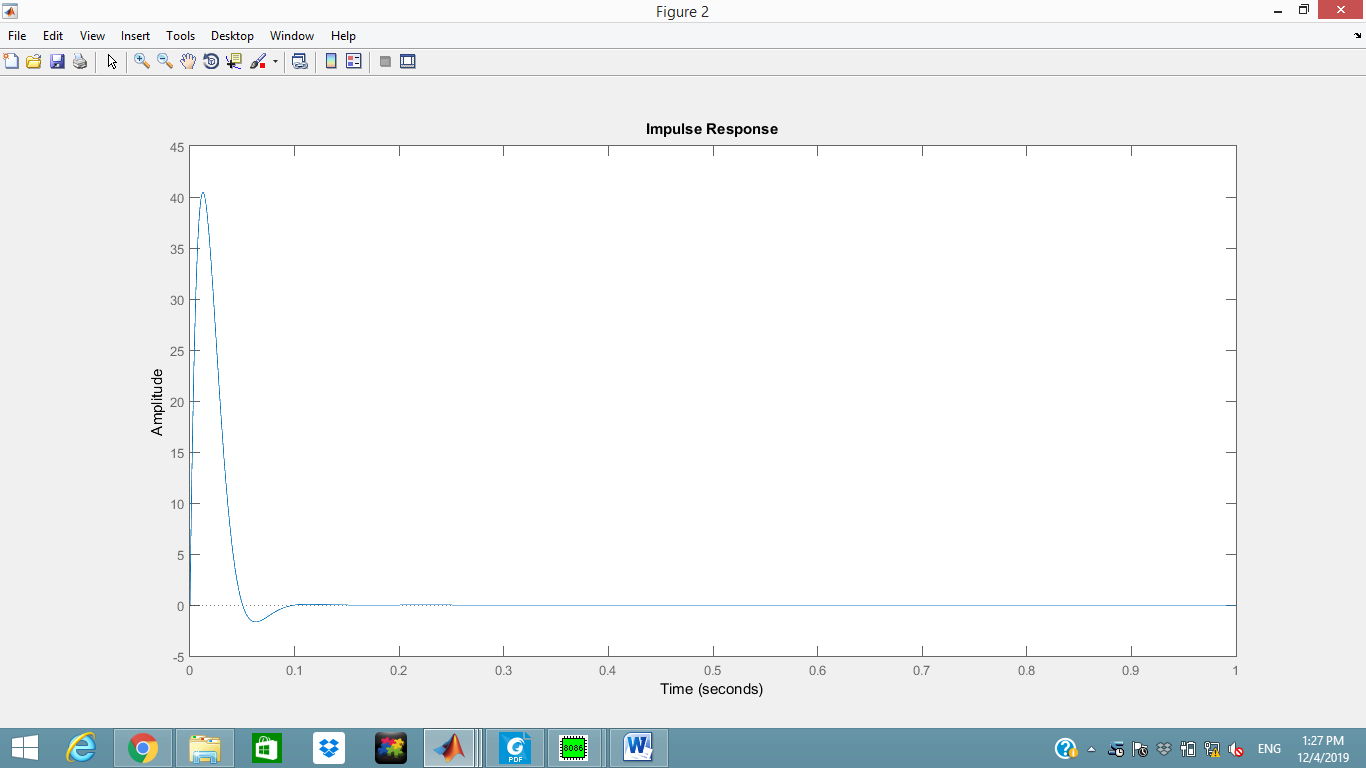
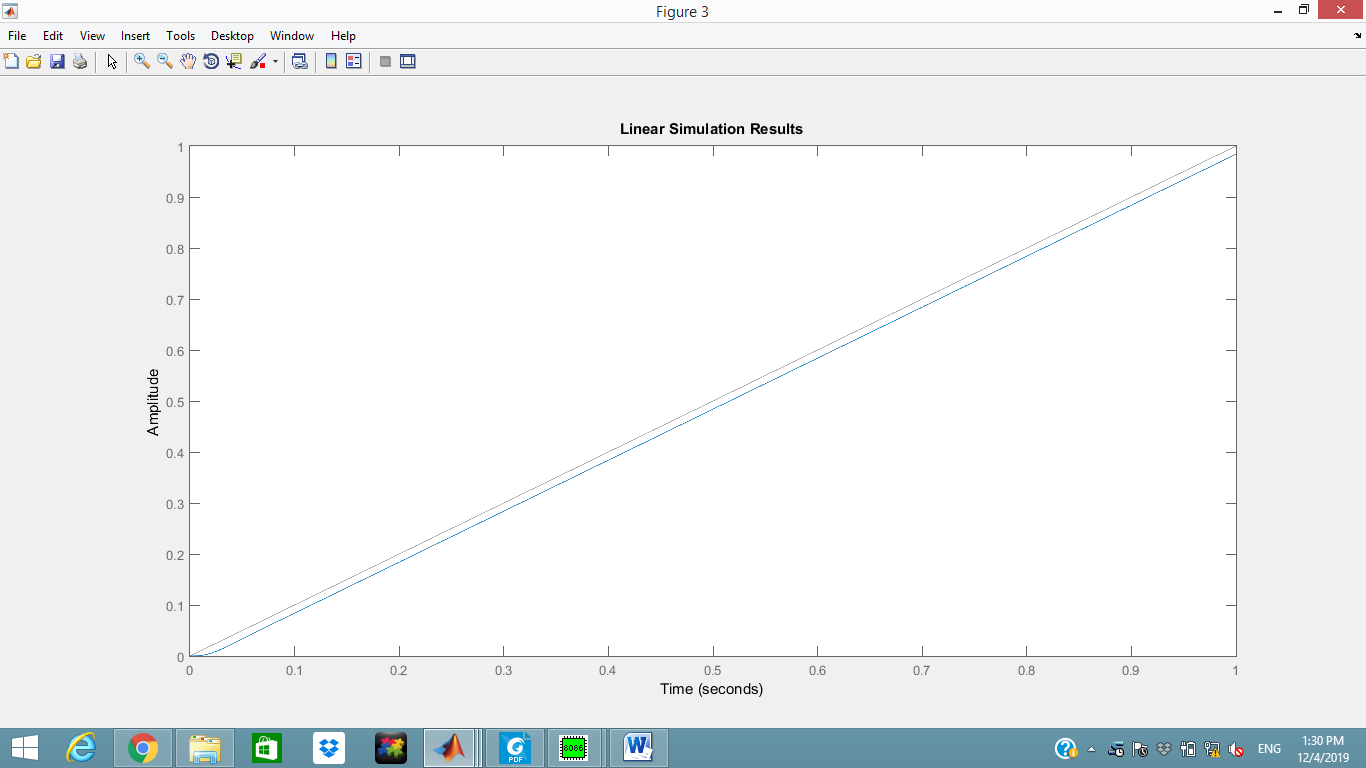
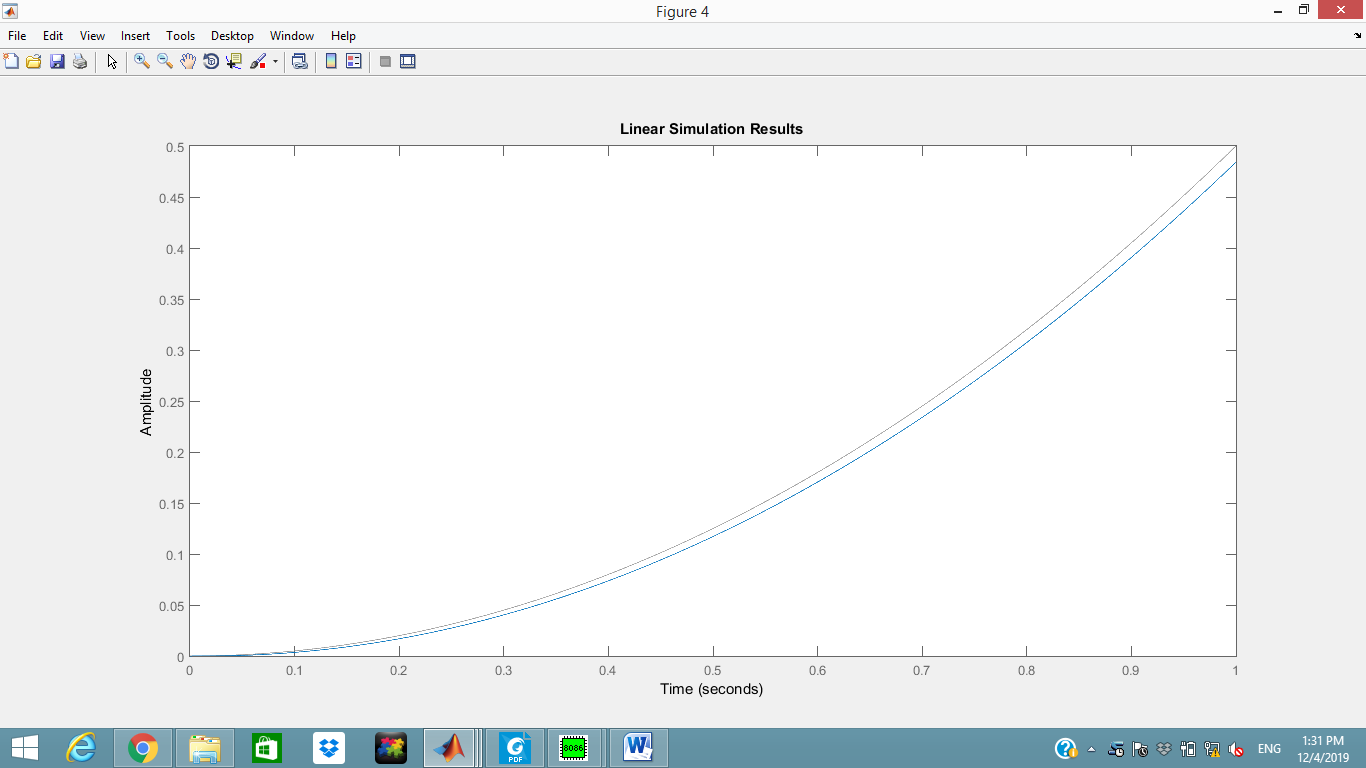
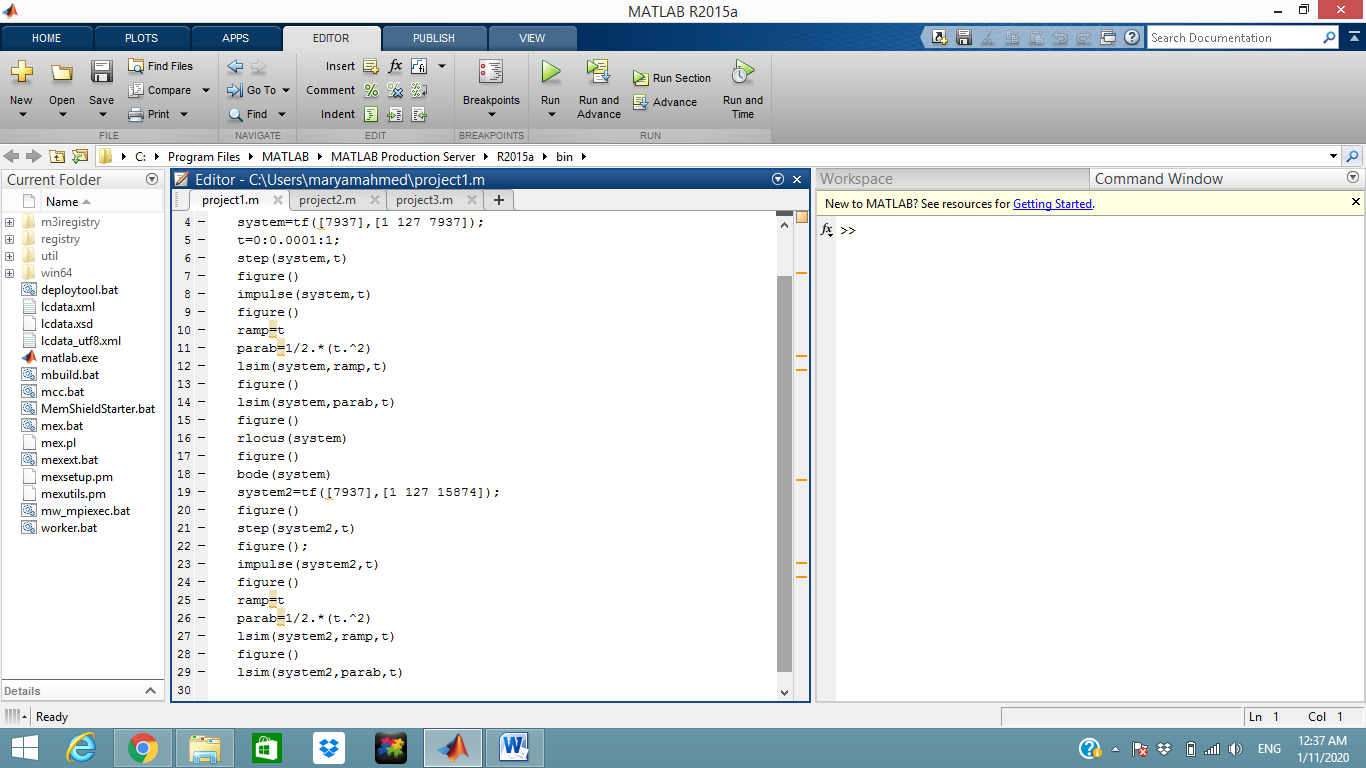
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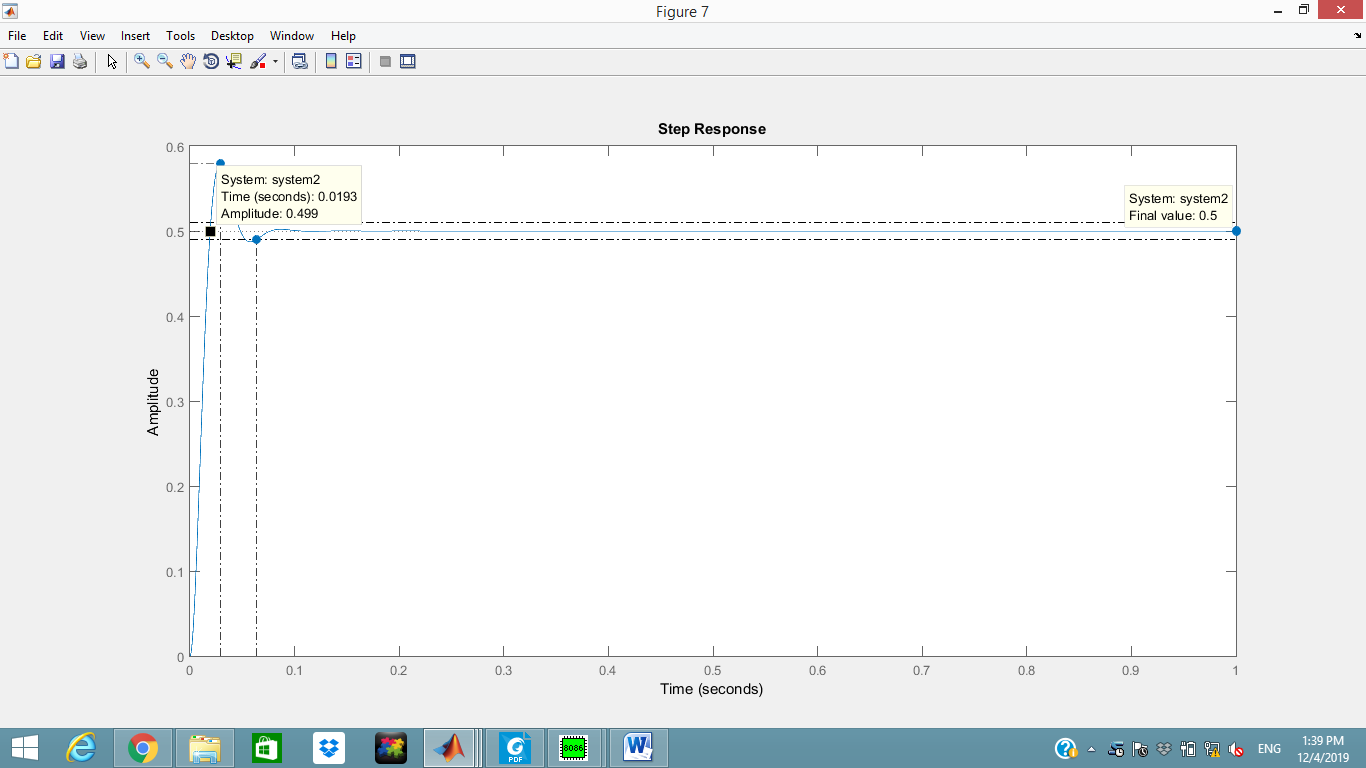


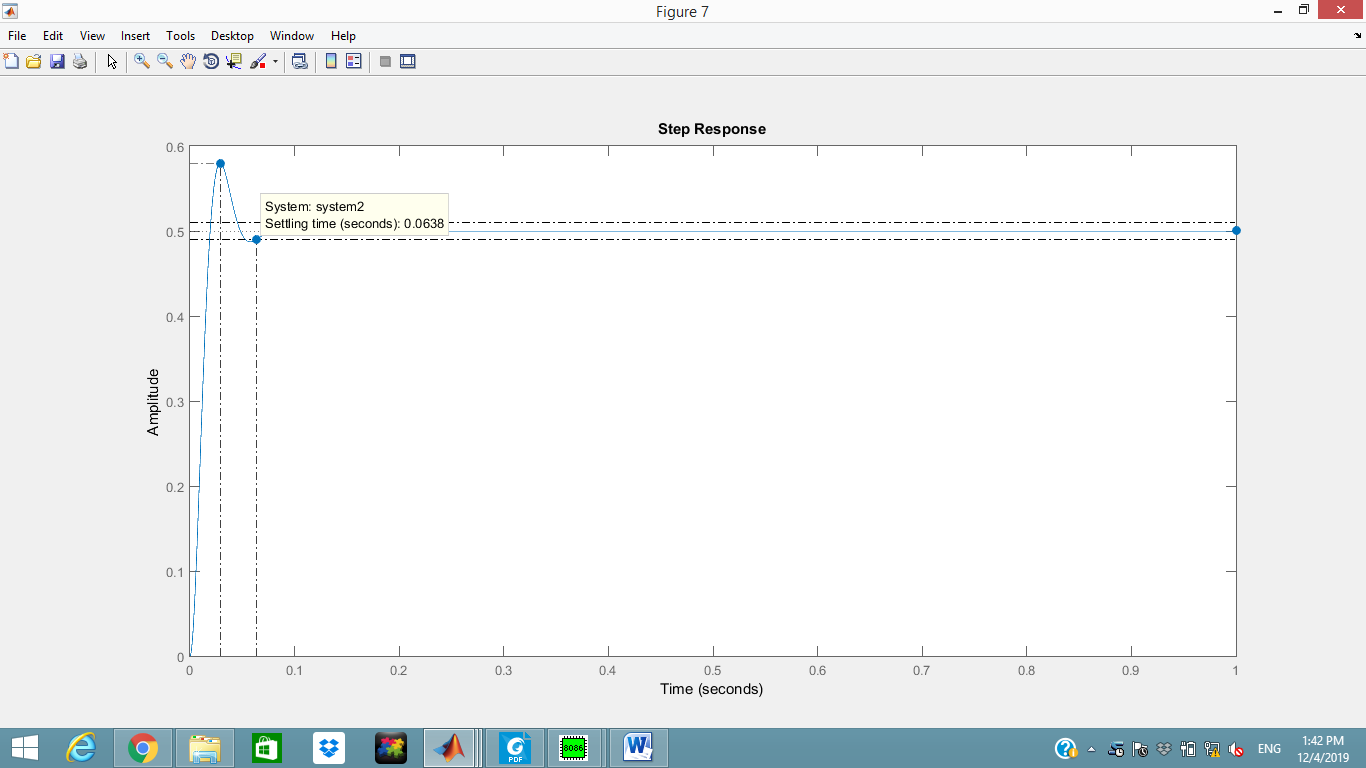


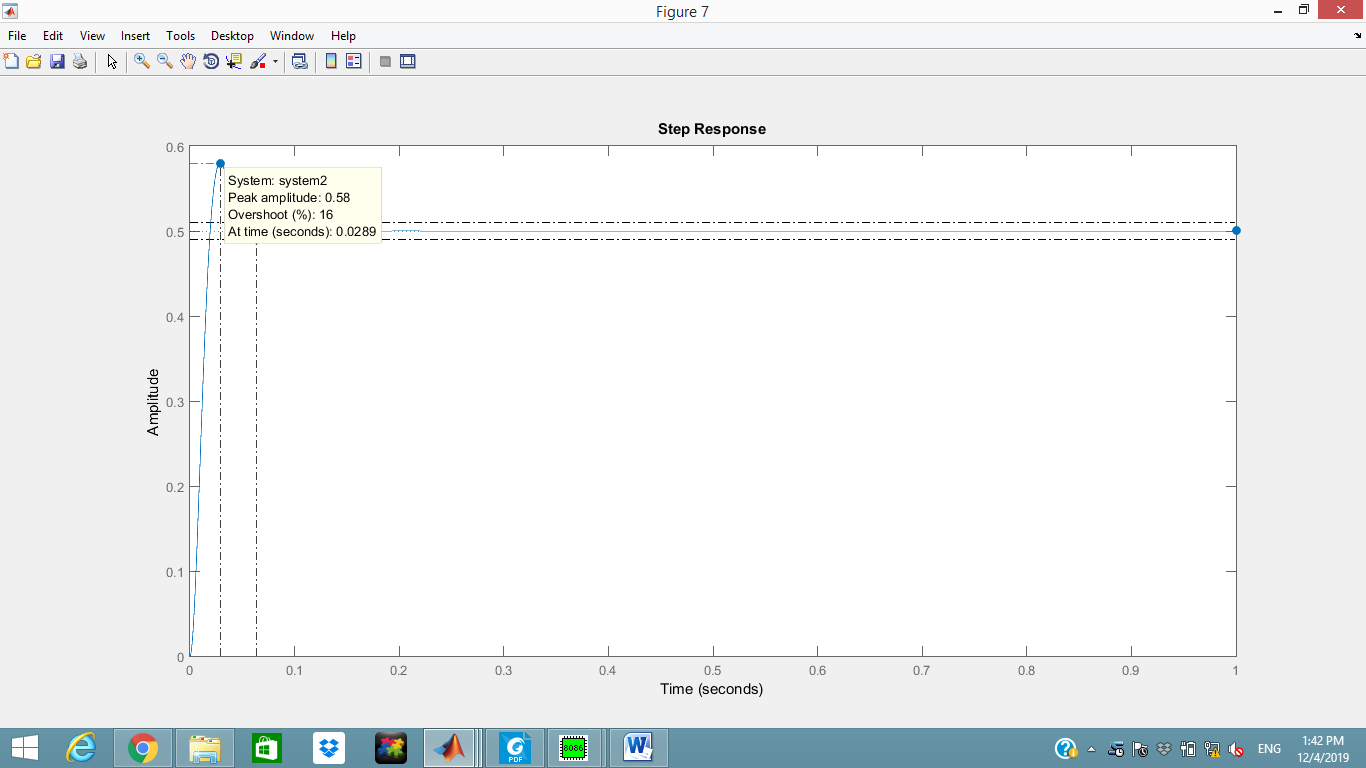


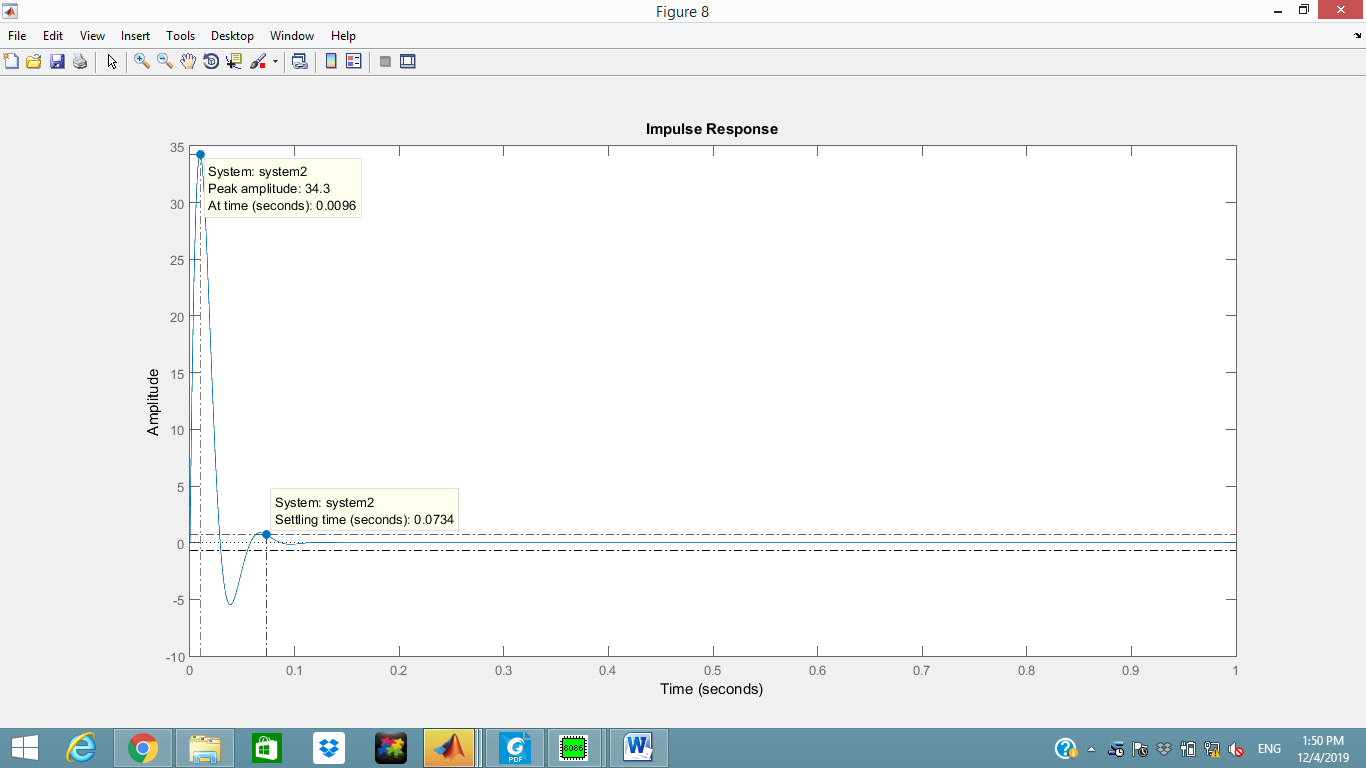


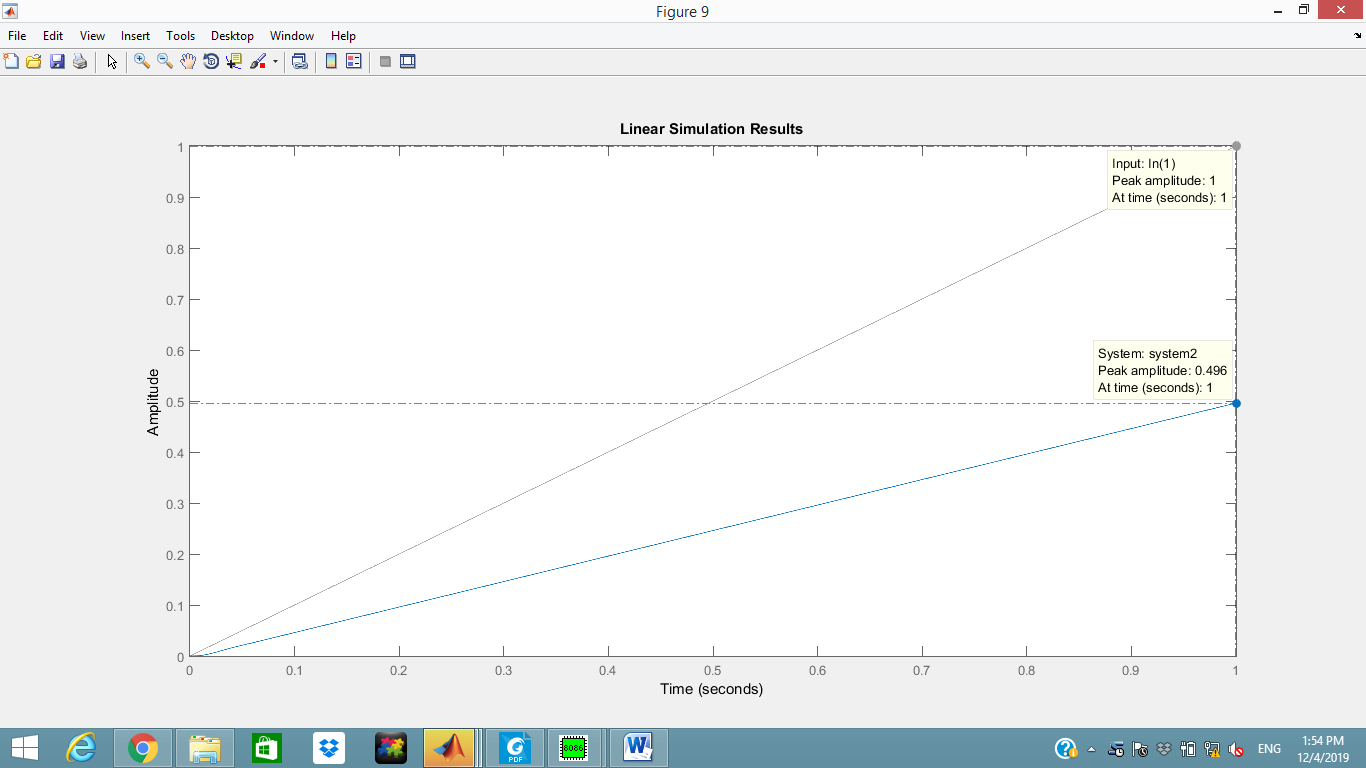
Feedback system transfer function: 

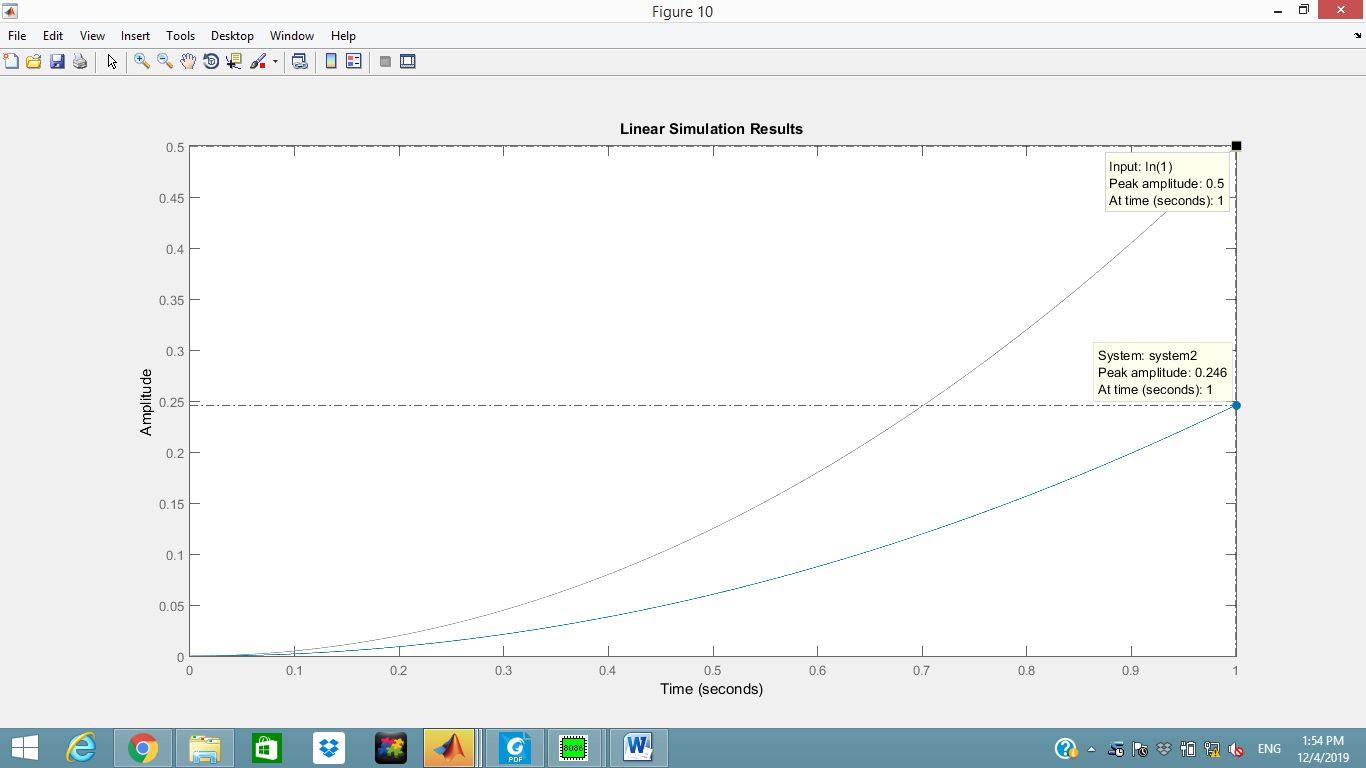


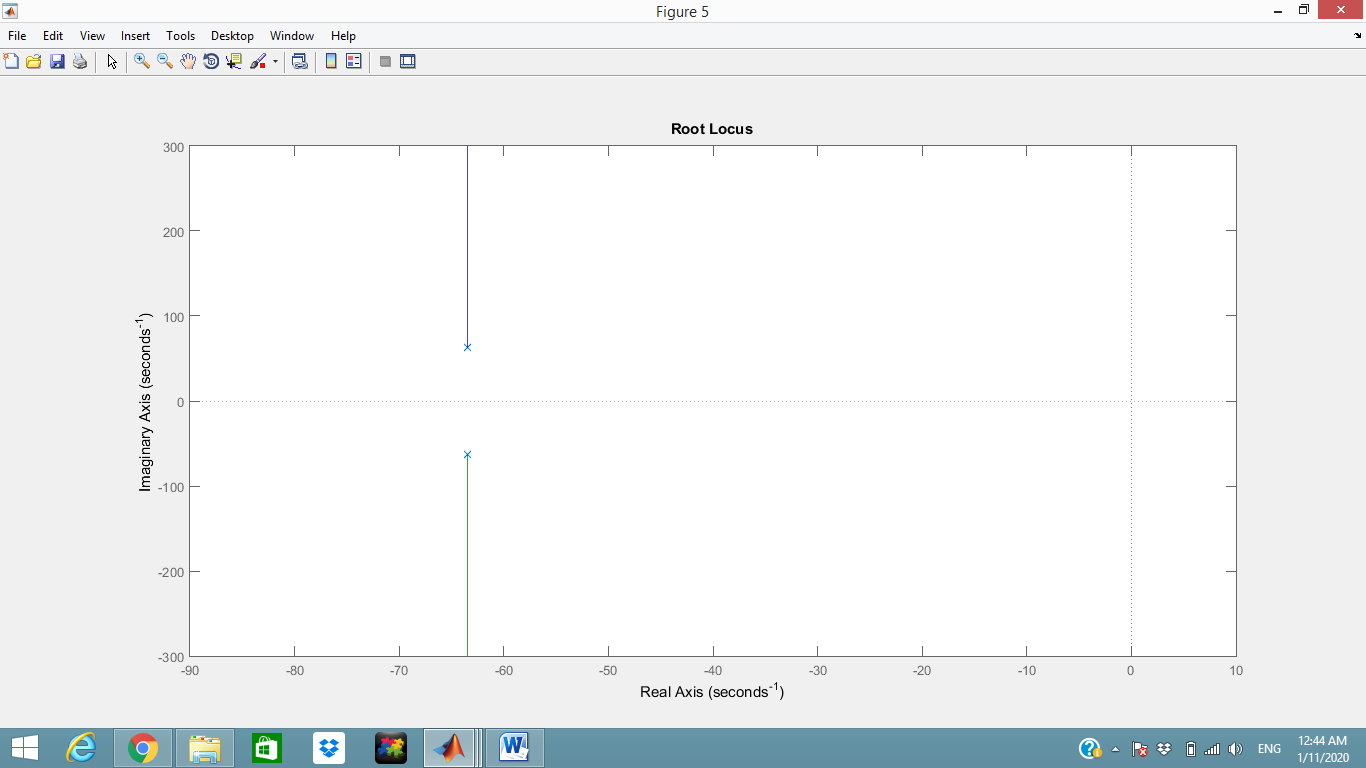


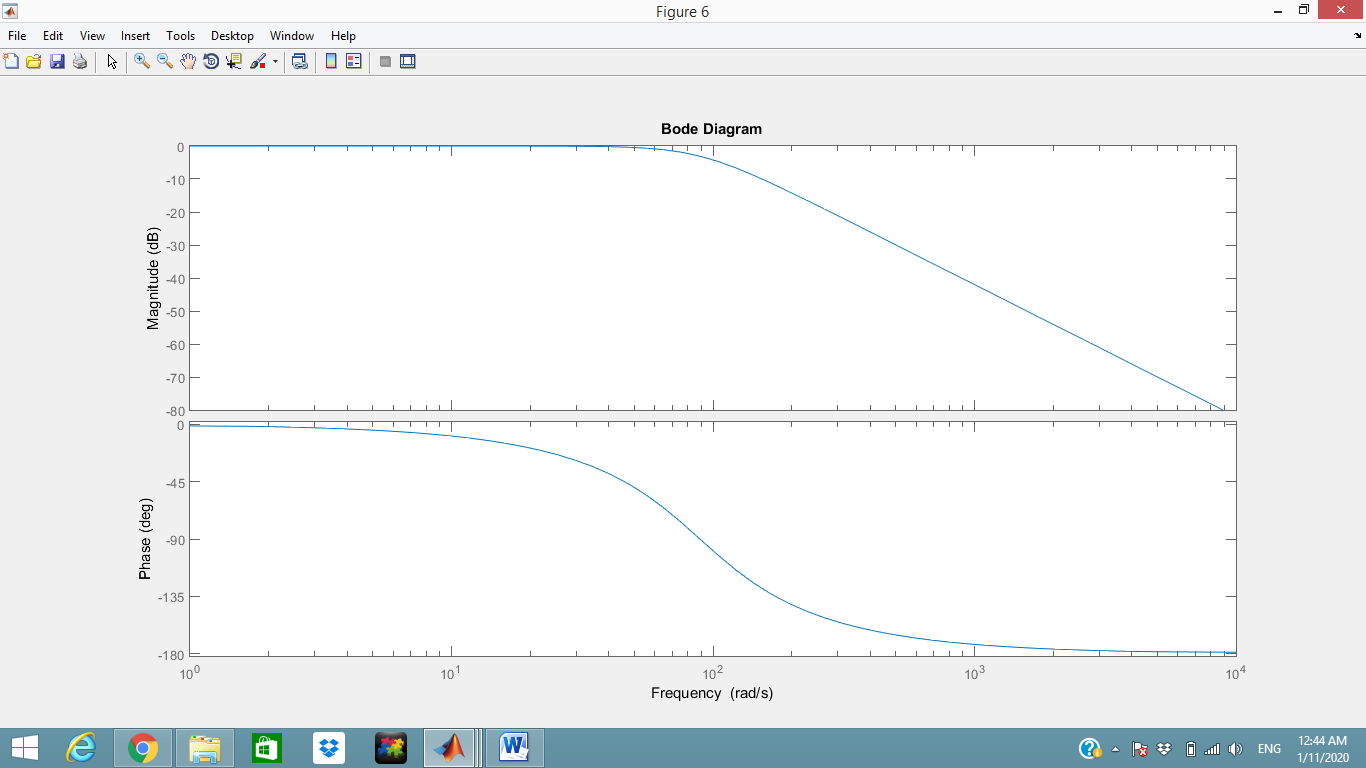




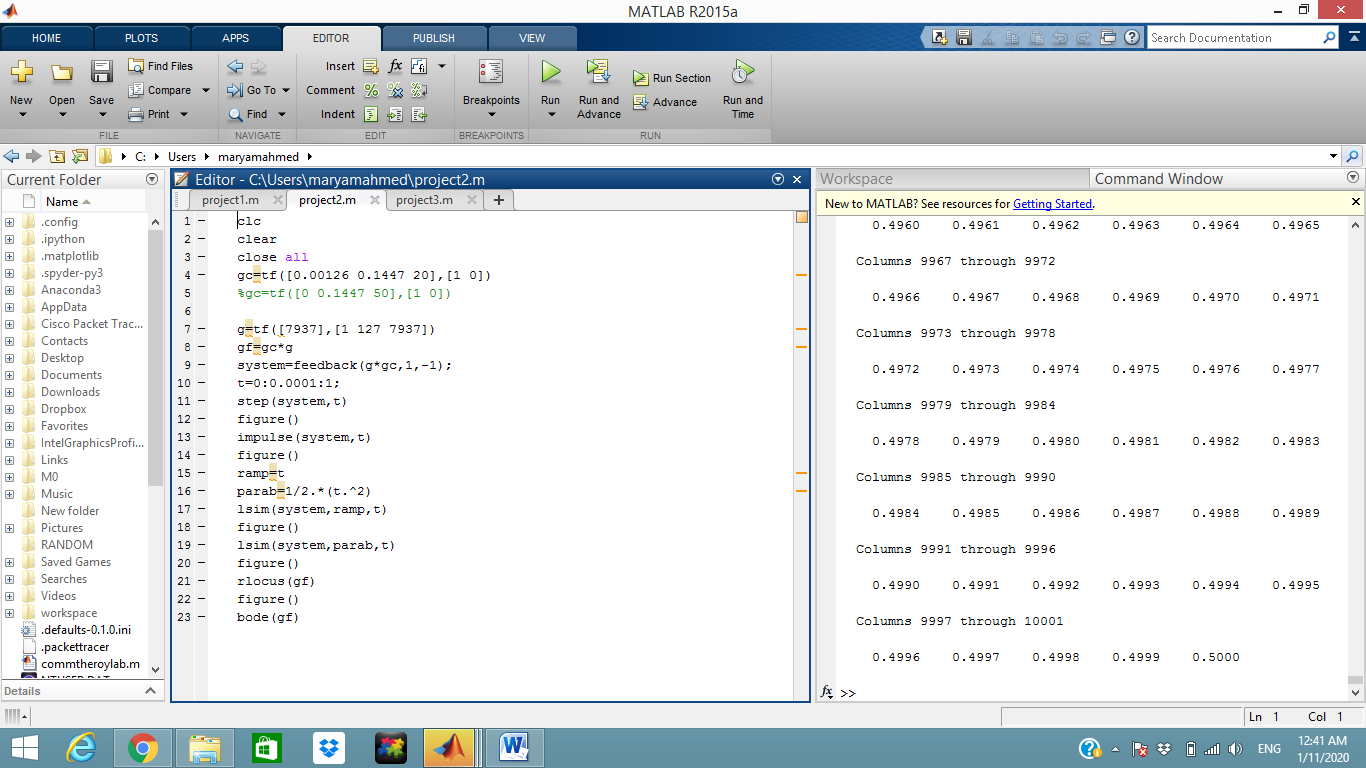


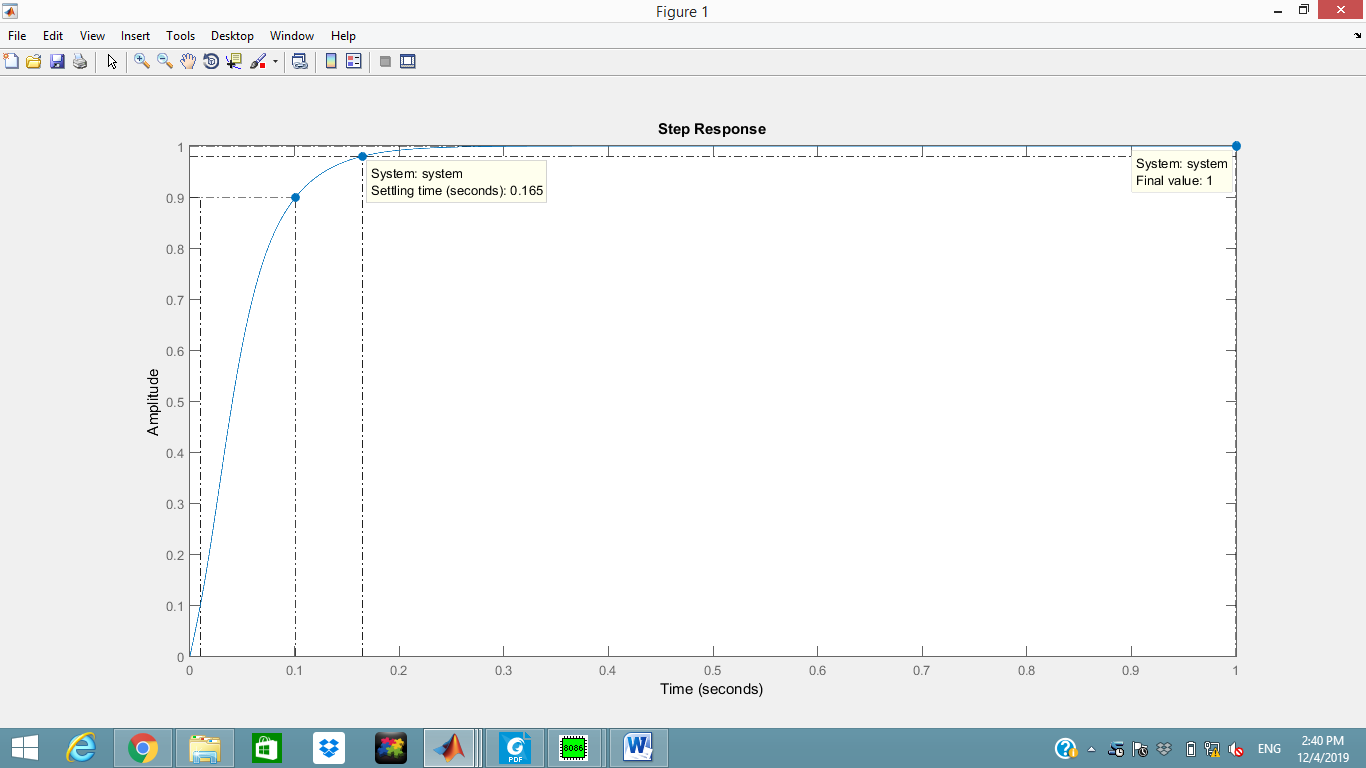


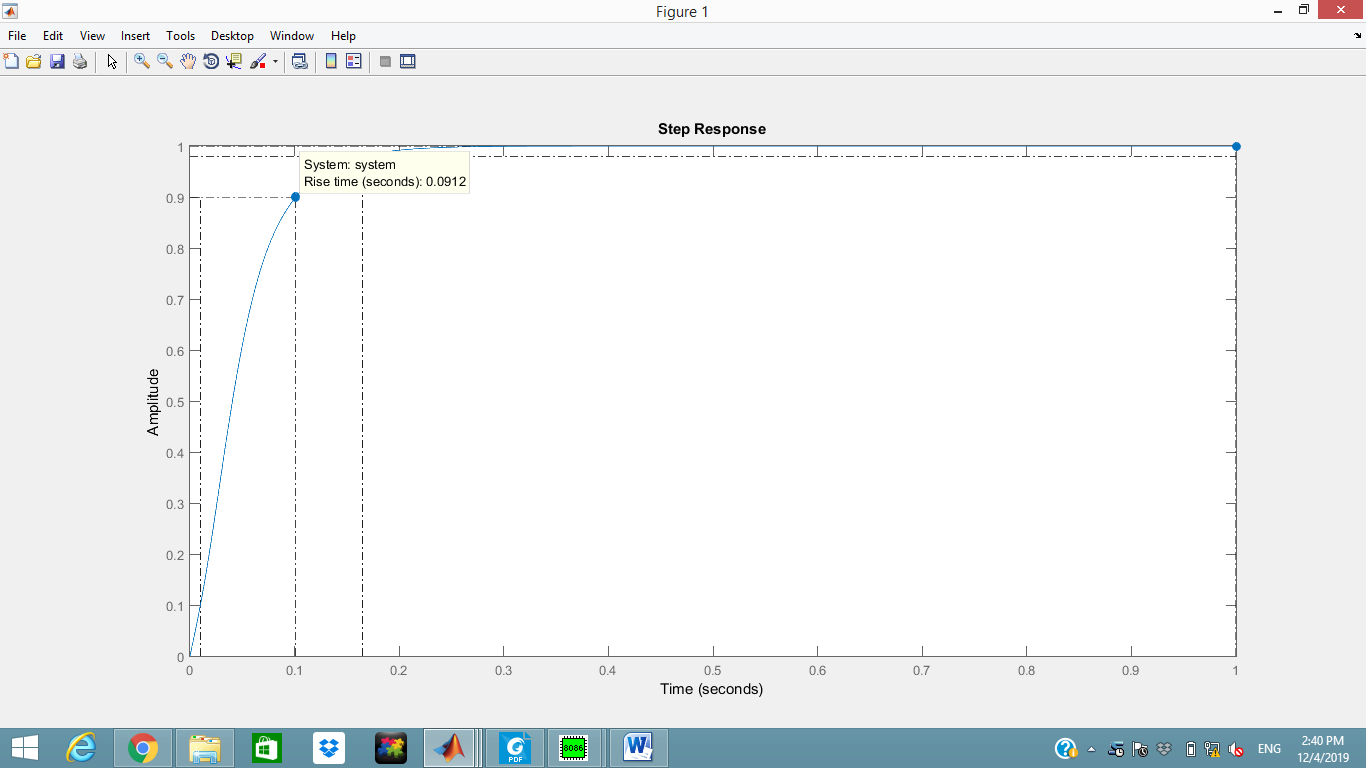


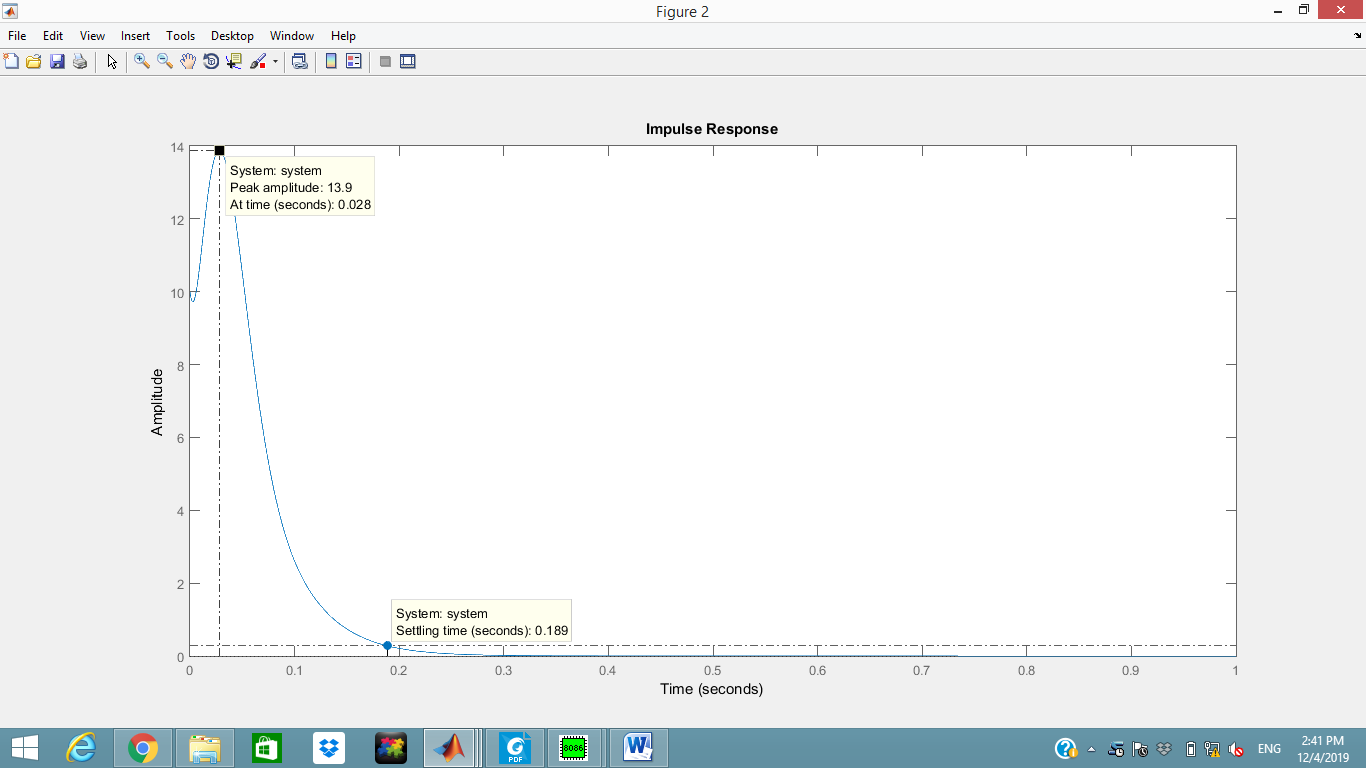


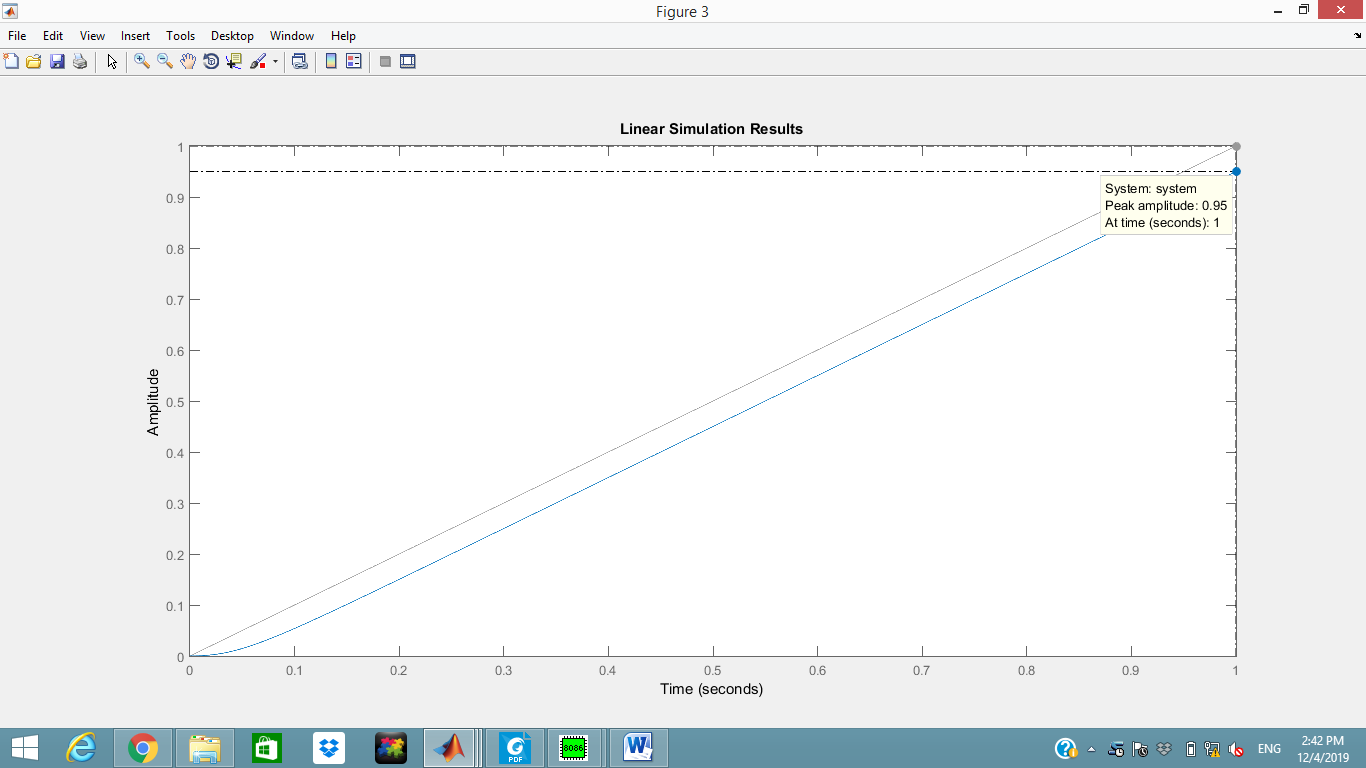
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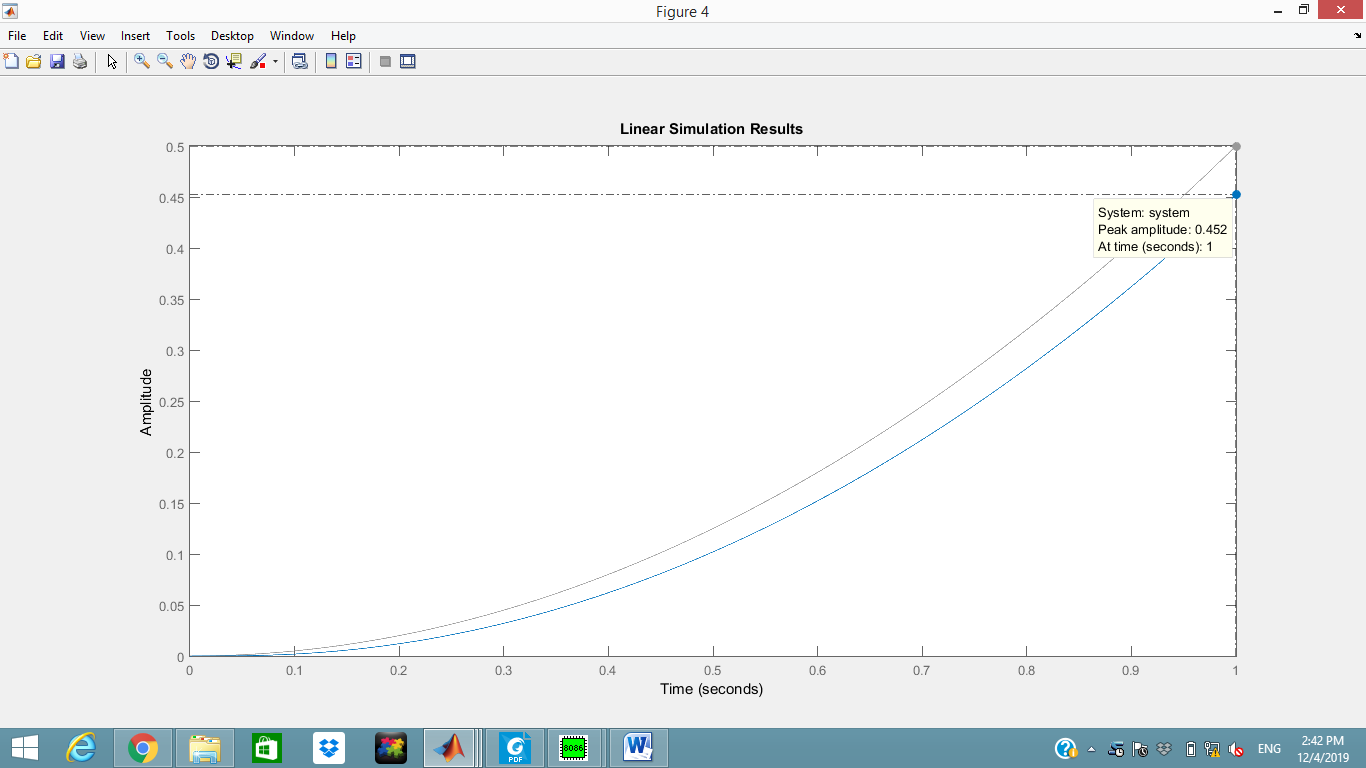


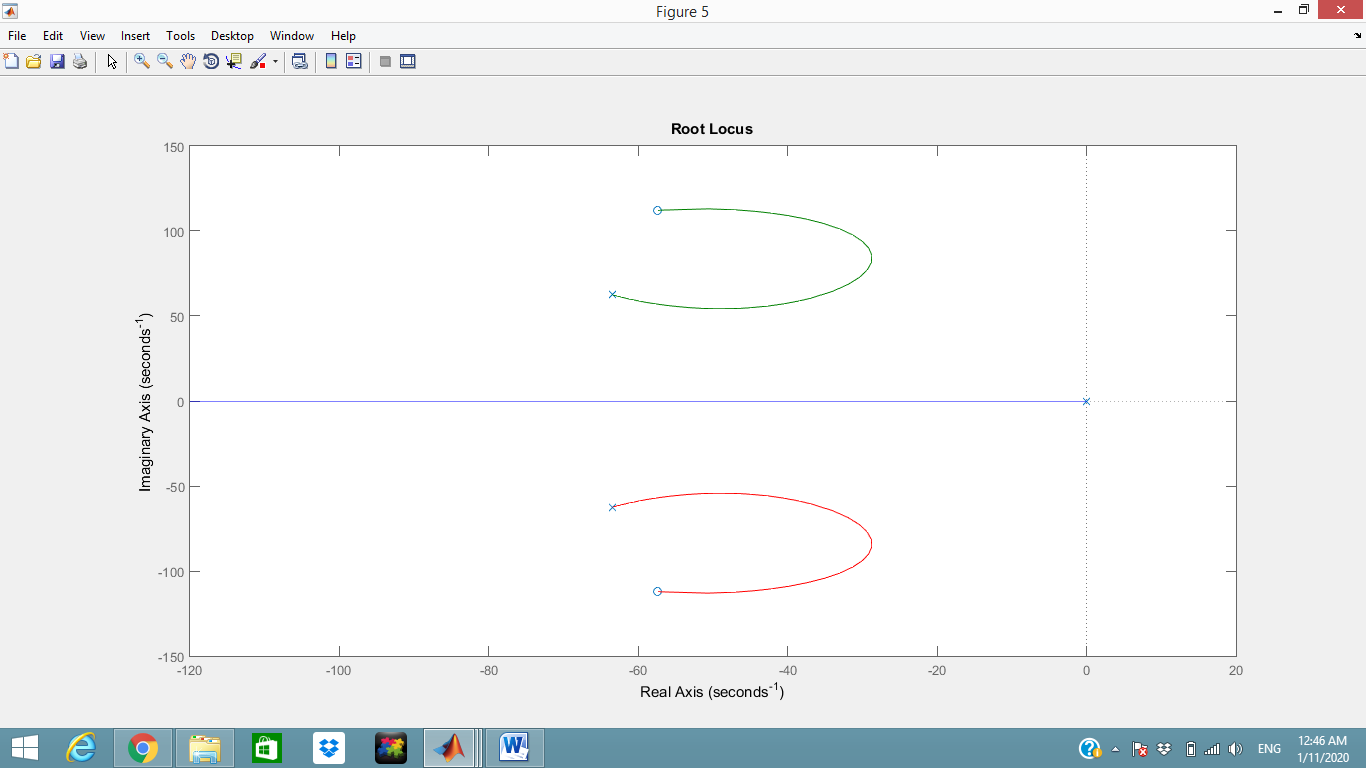


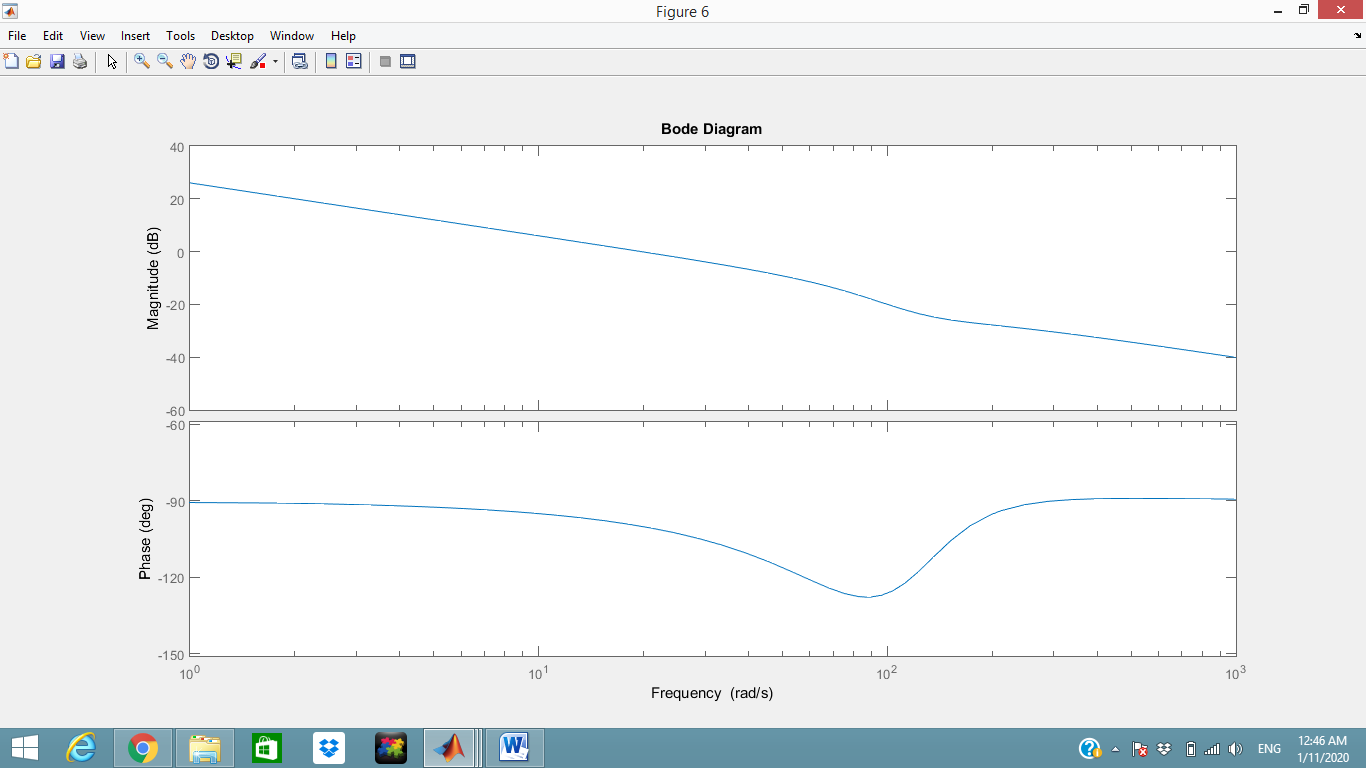




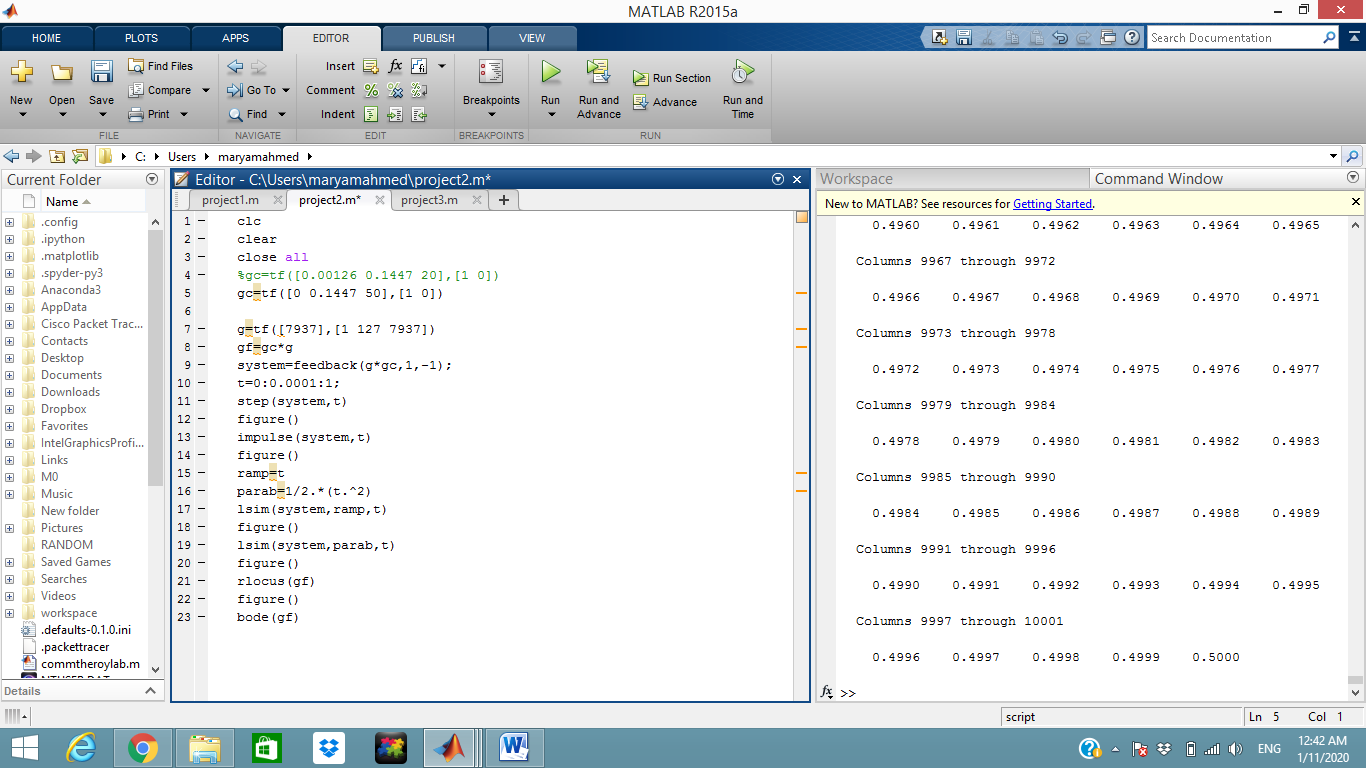


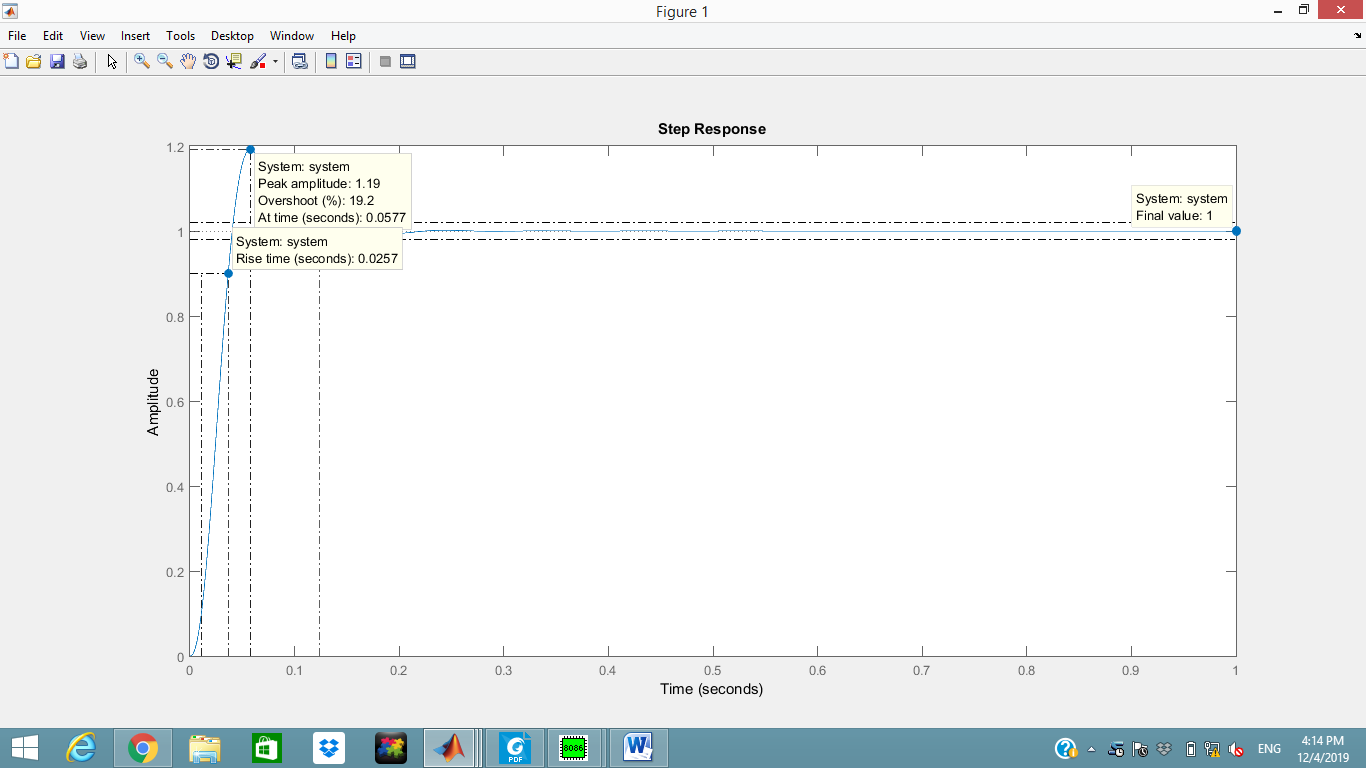


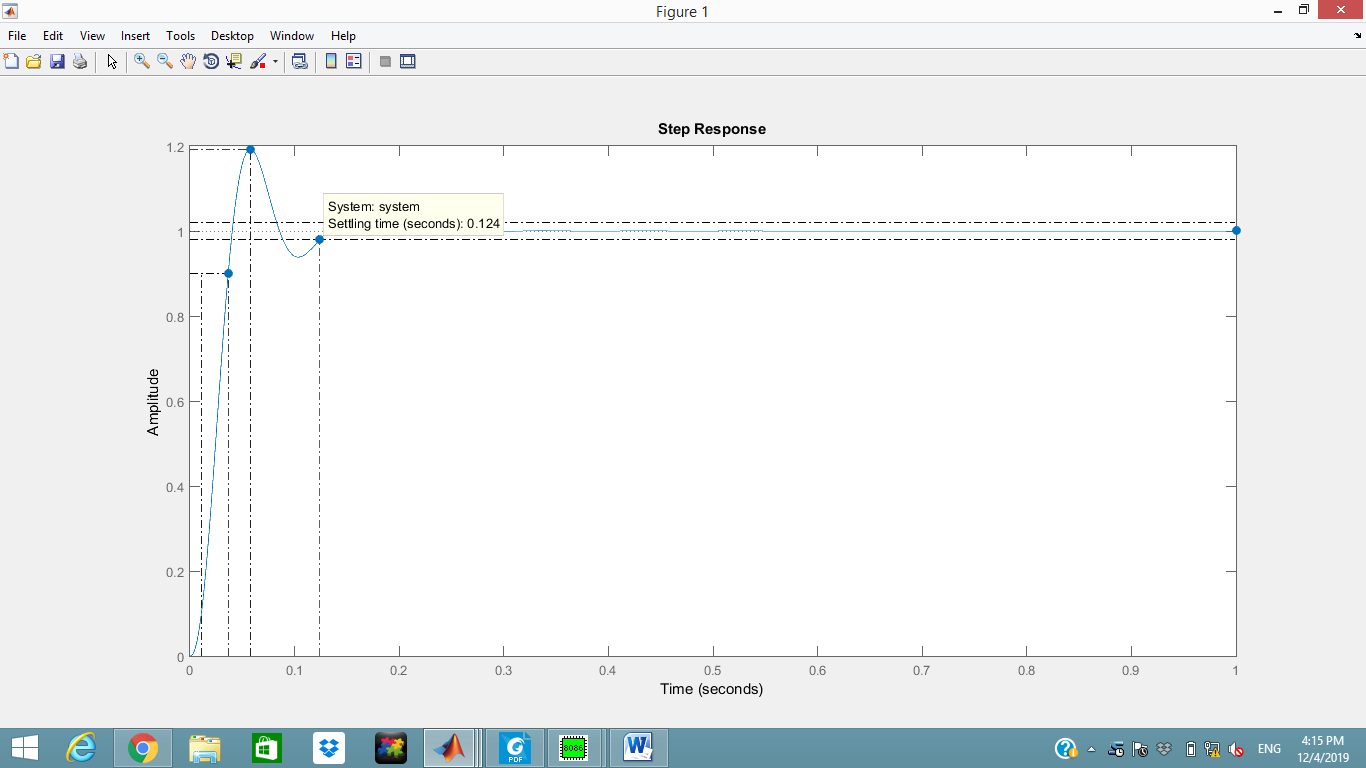


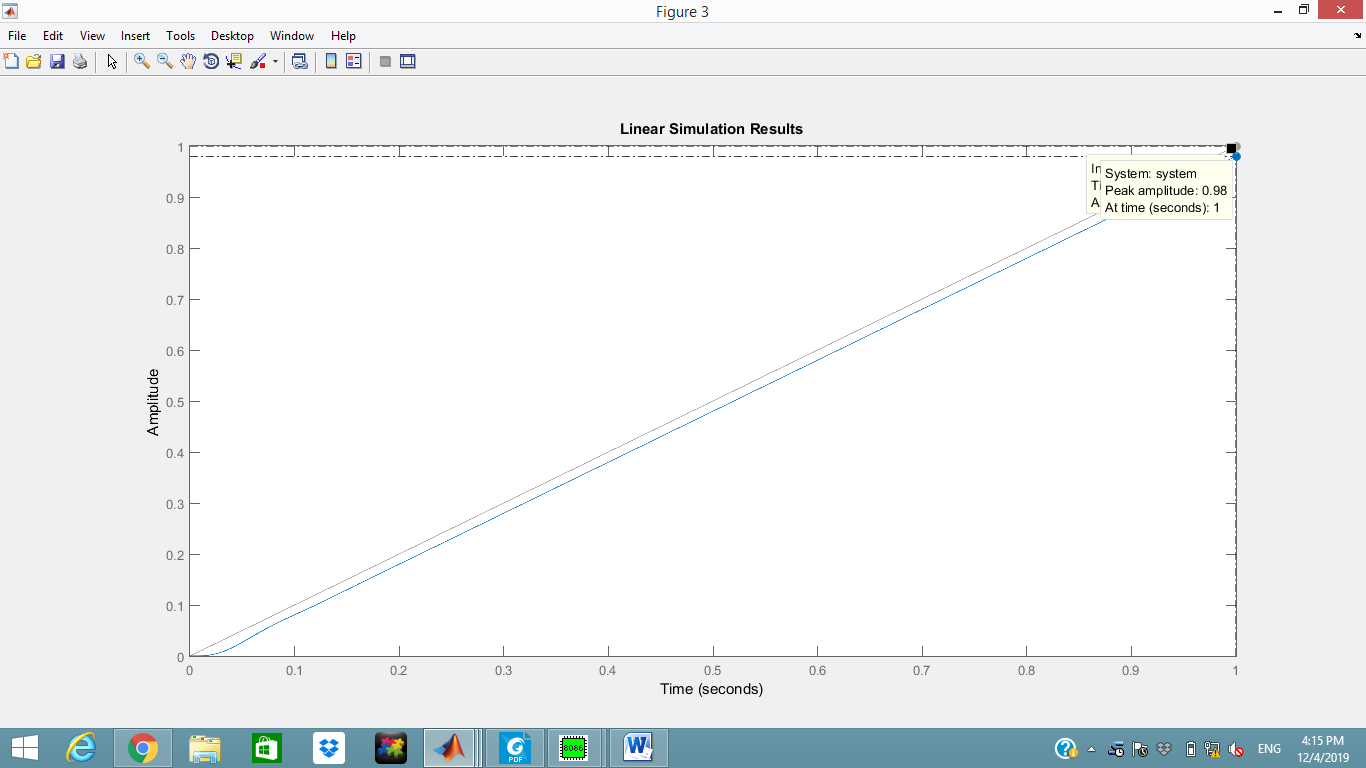


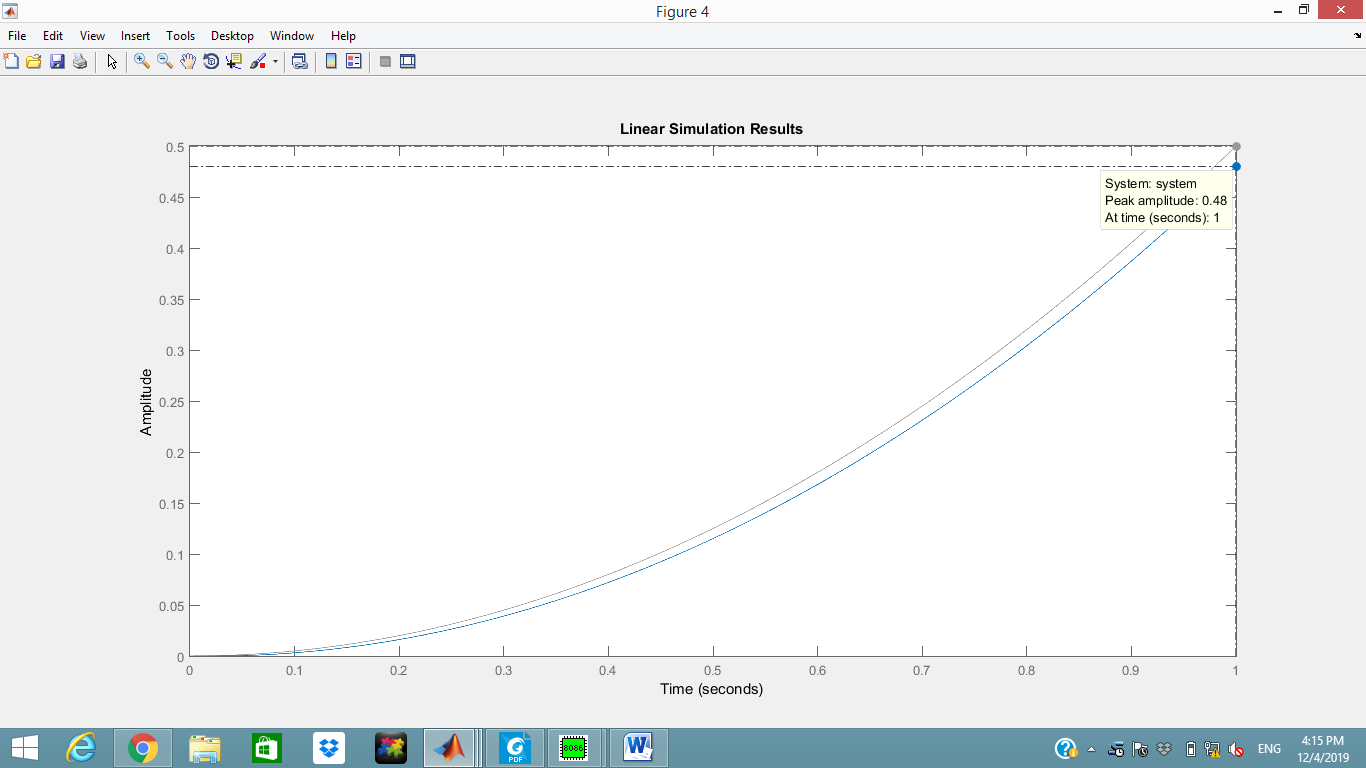
PID with tuning:

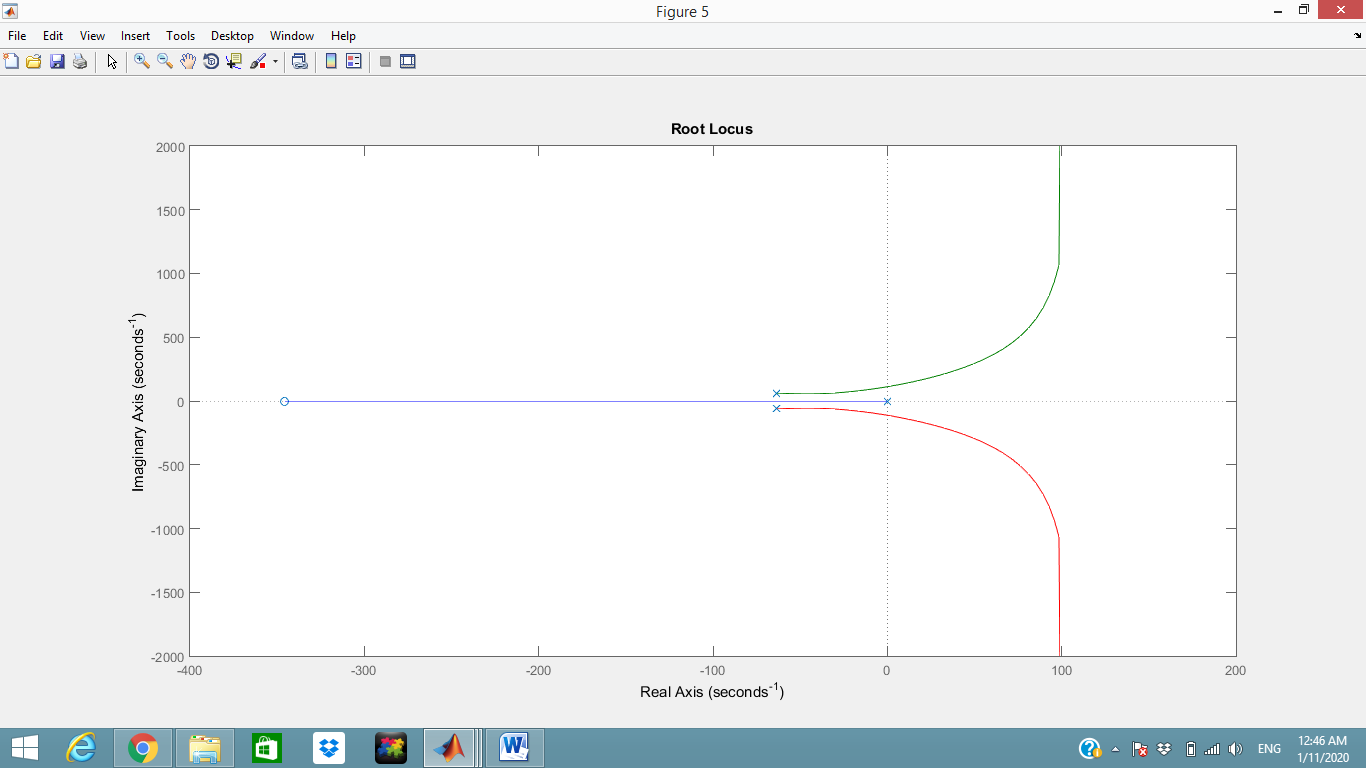


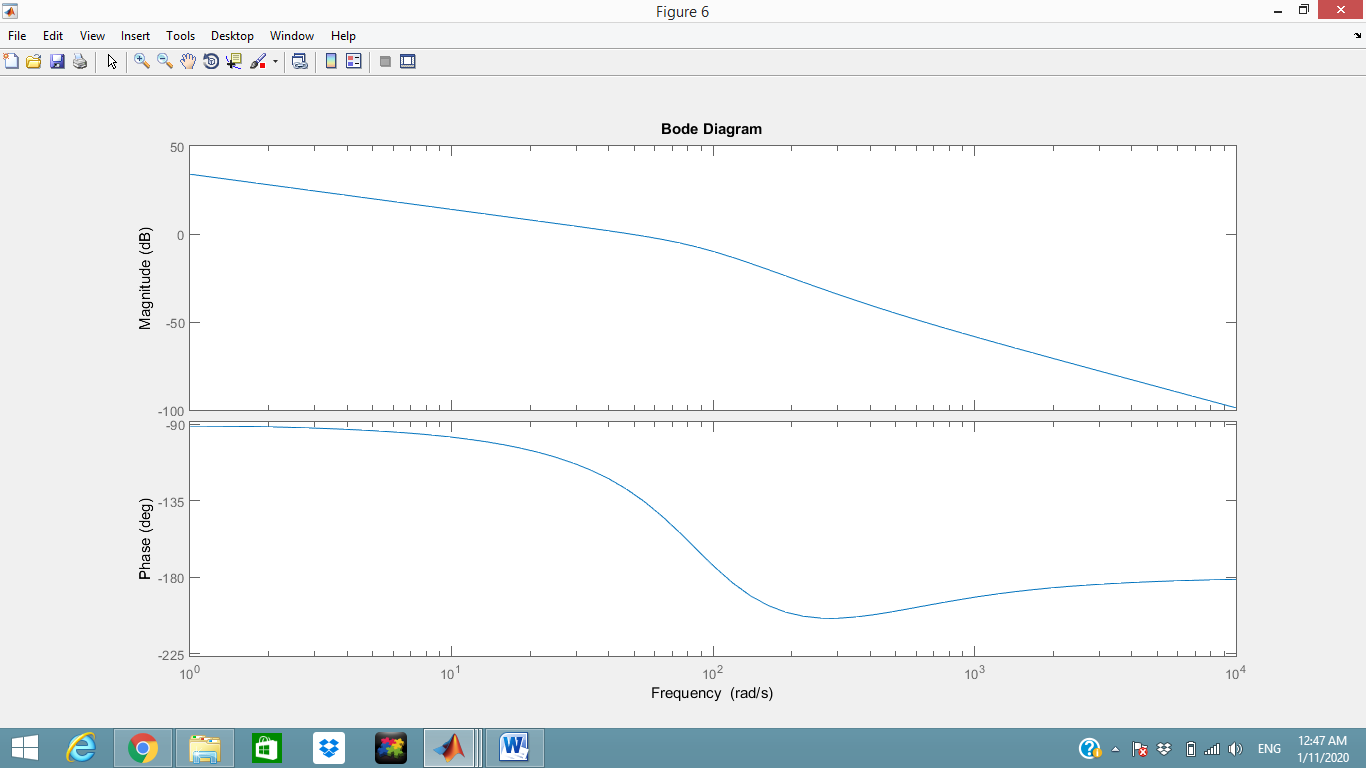




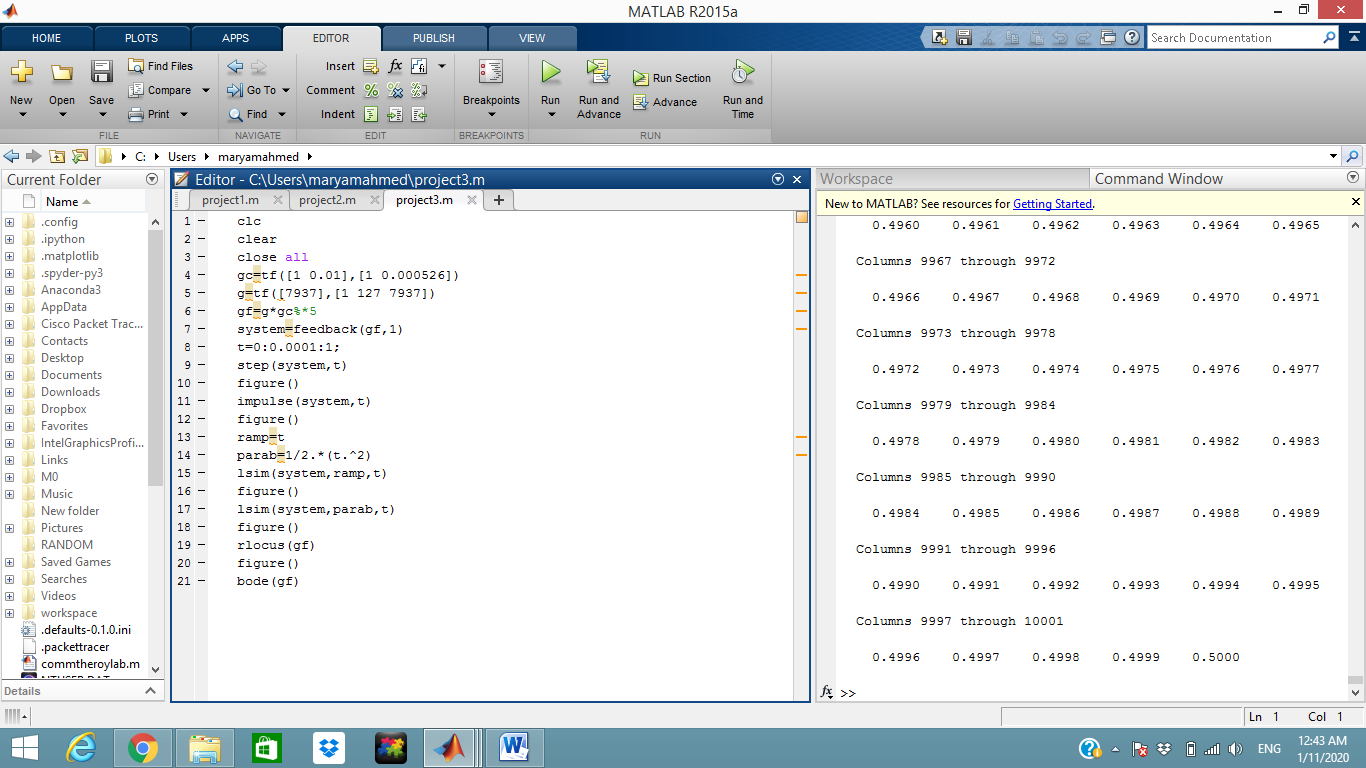


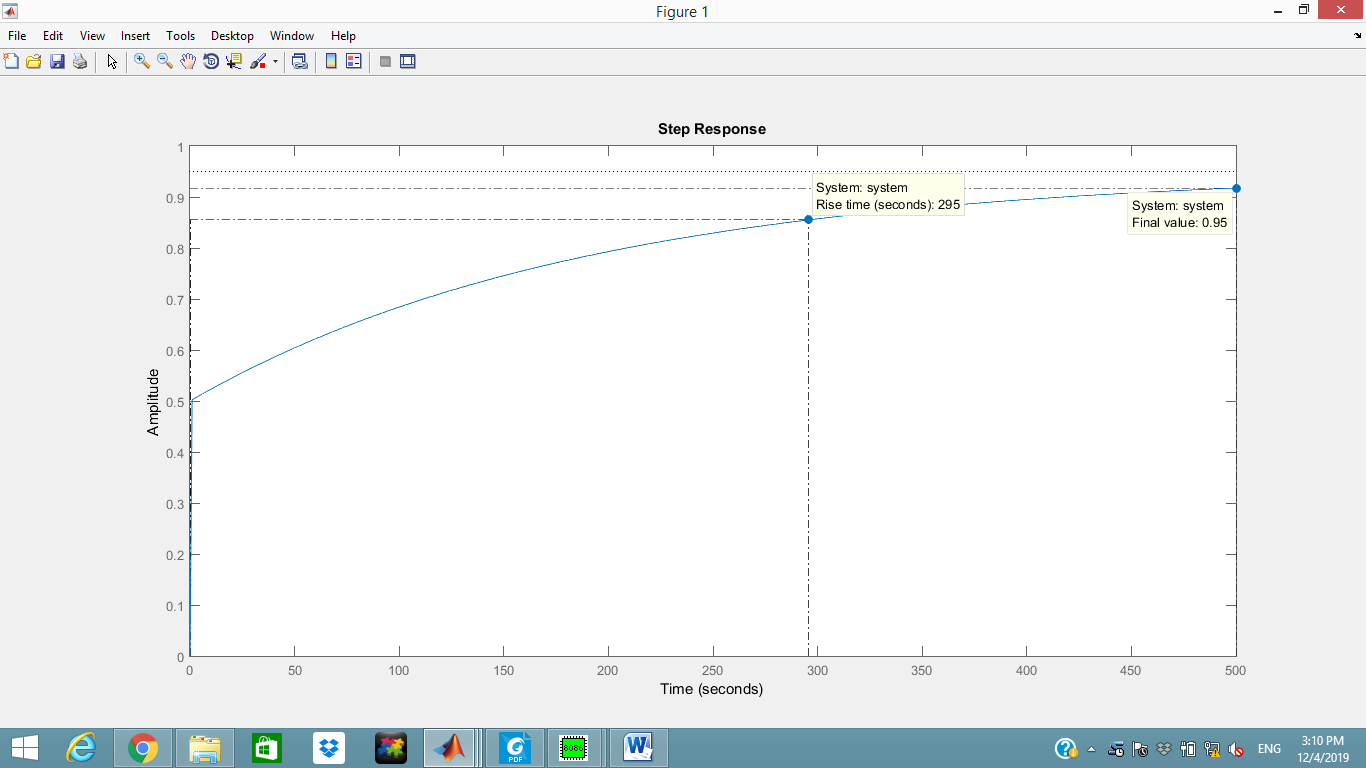


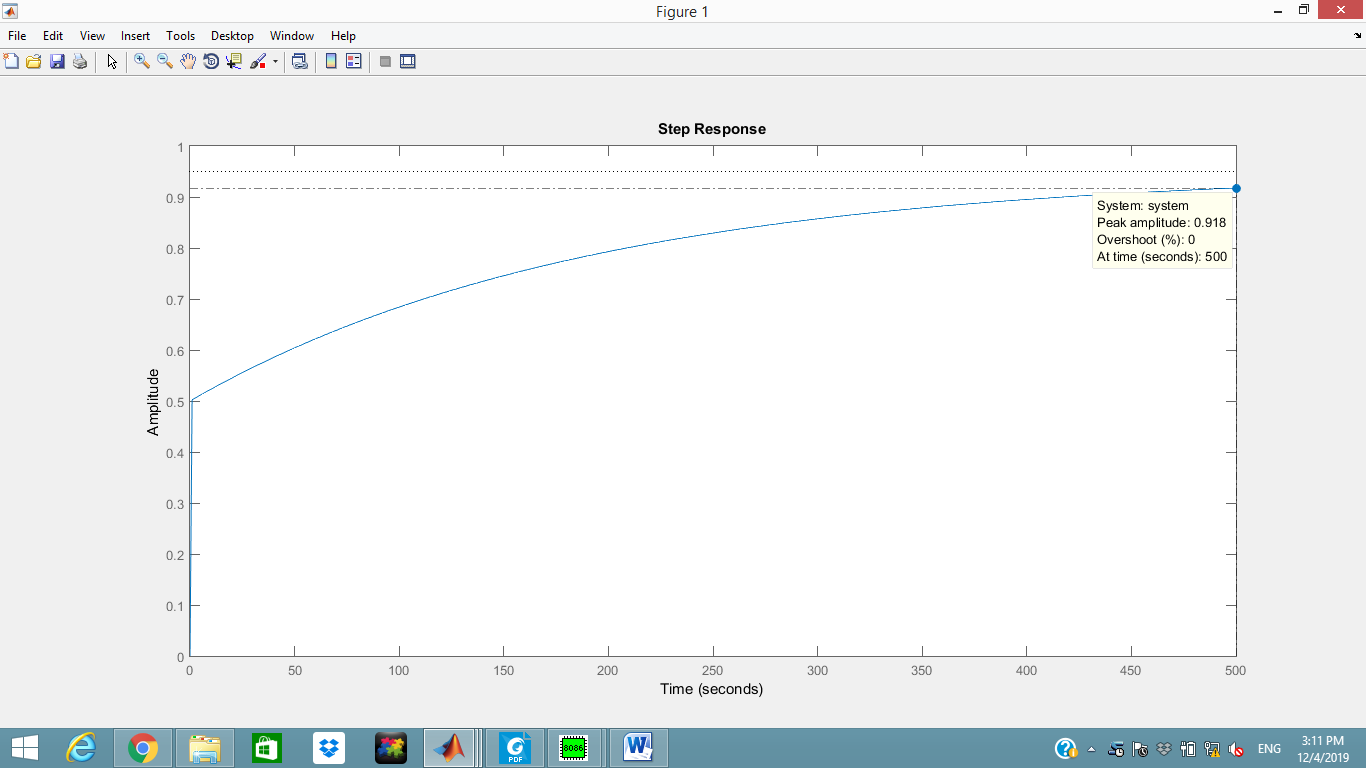


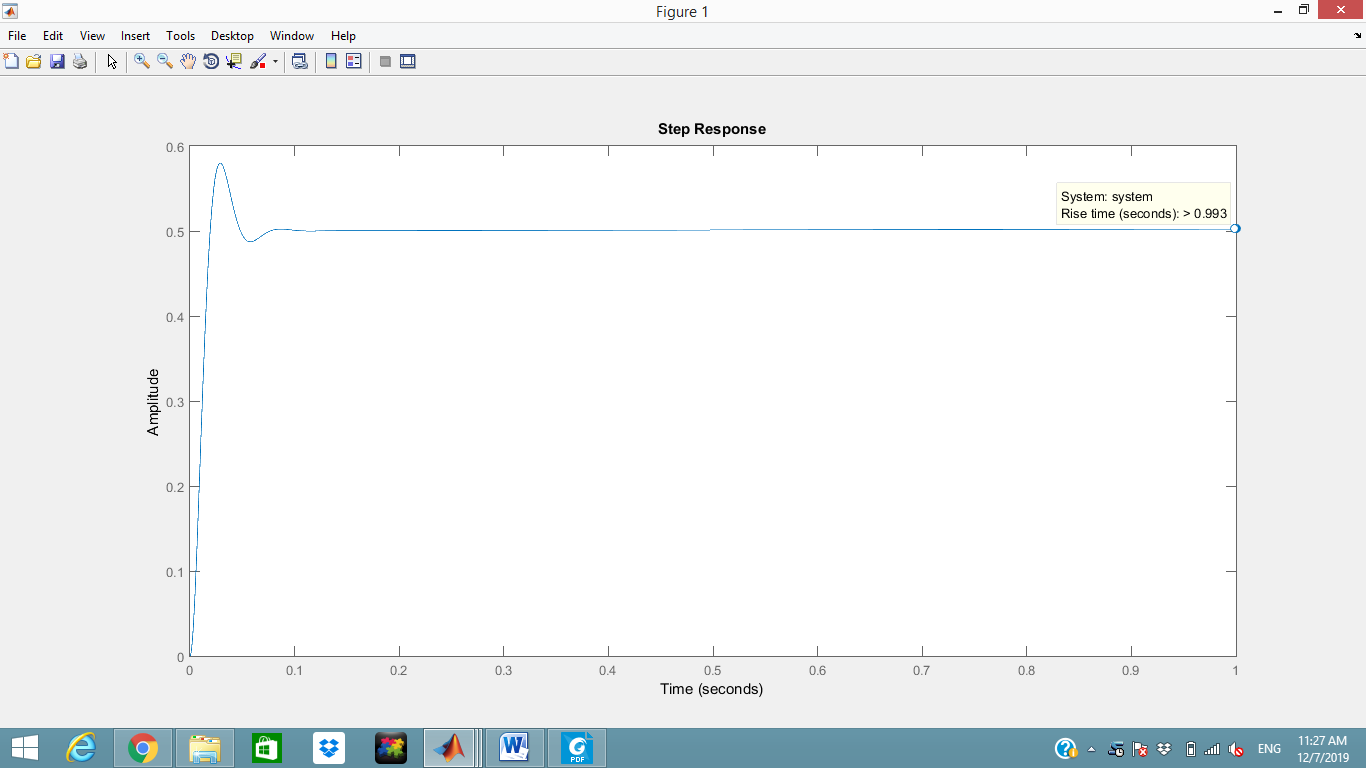


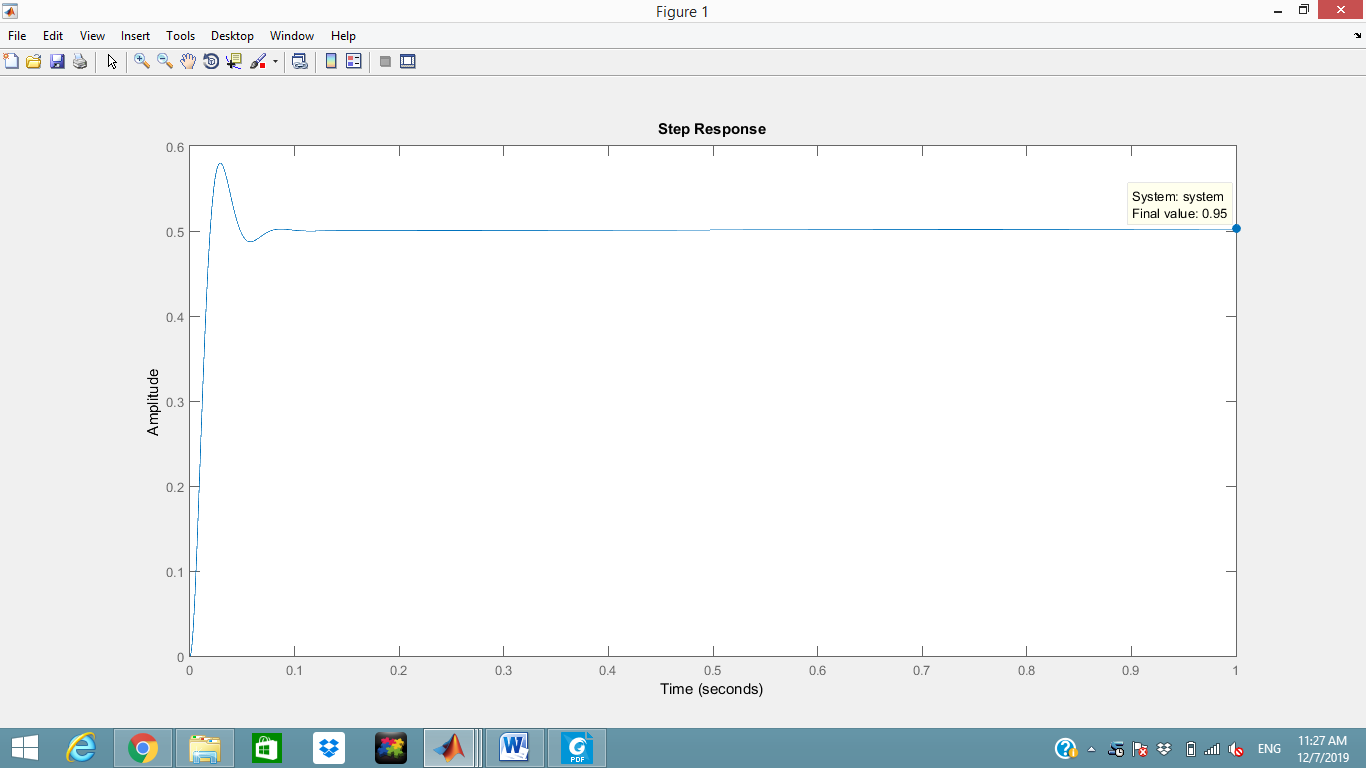
Lag compensator:

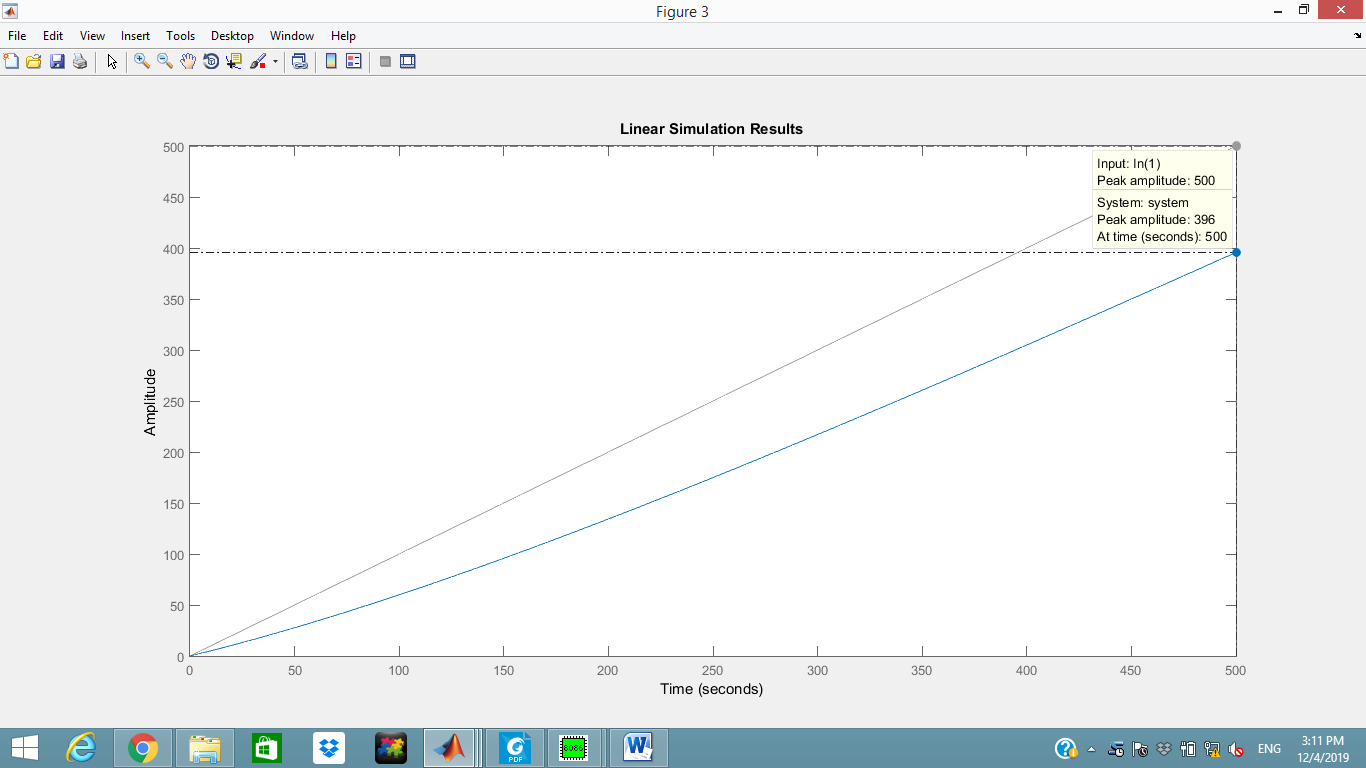


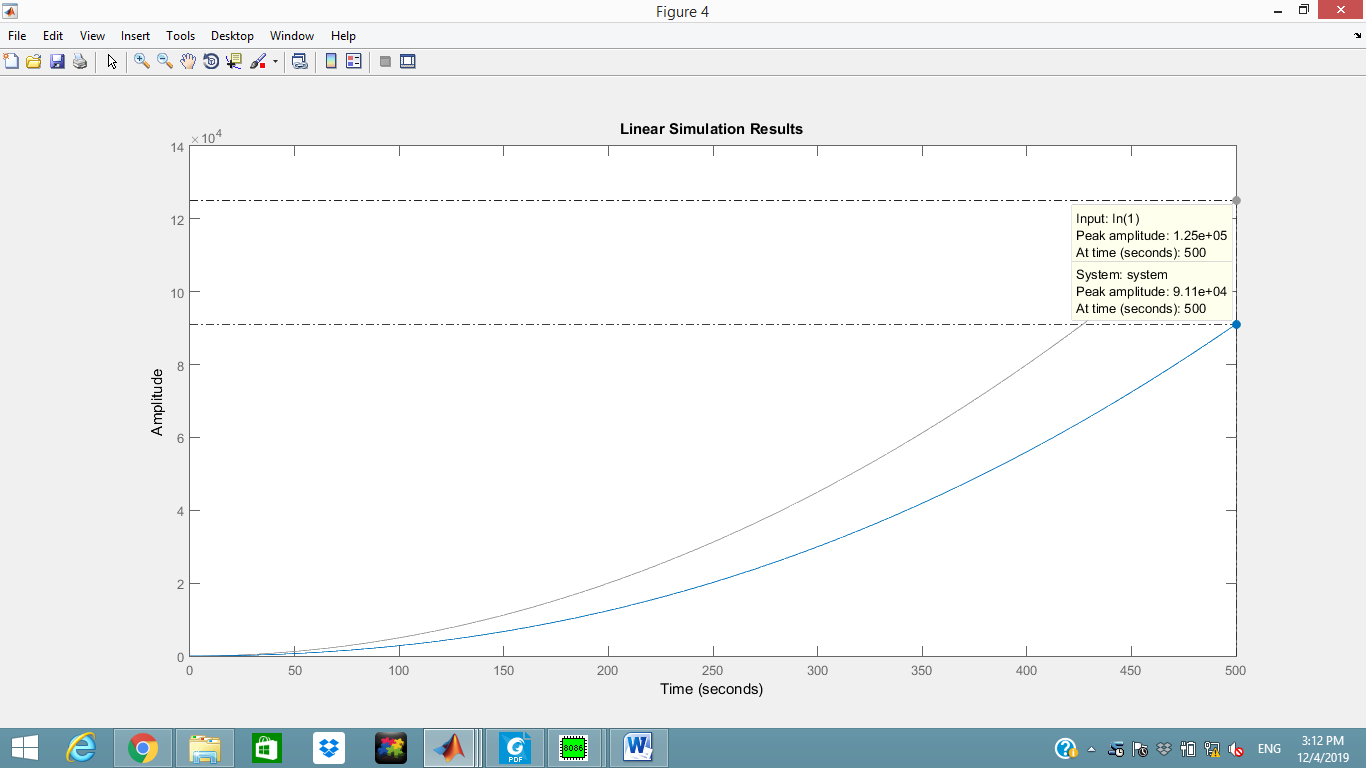


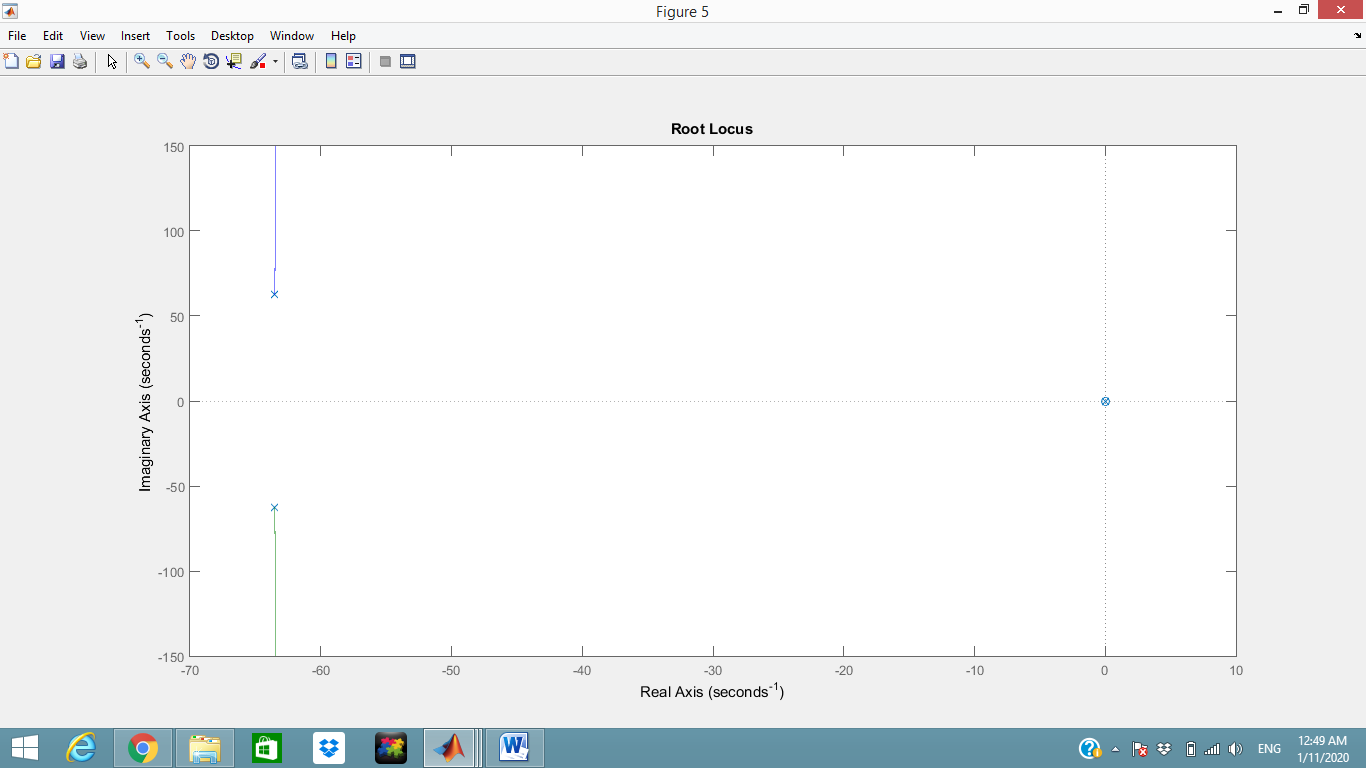


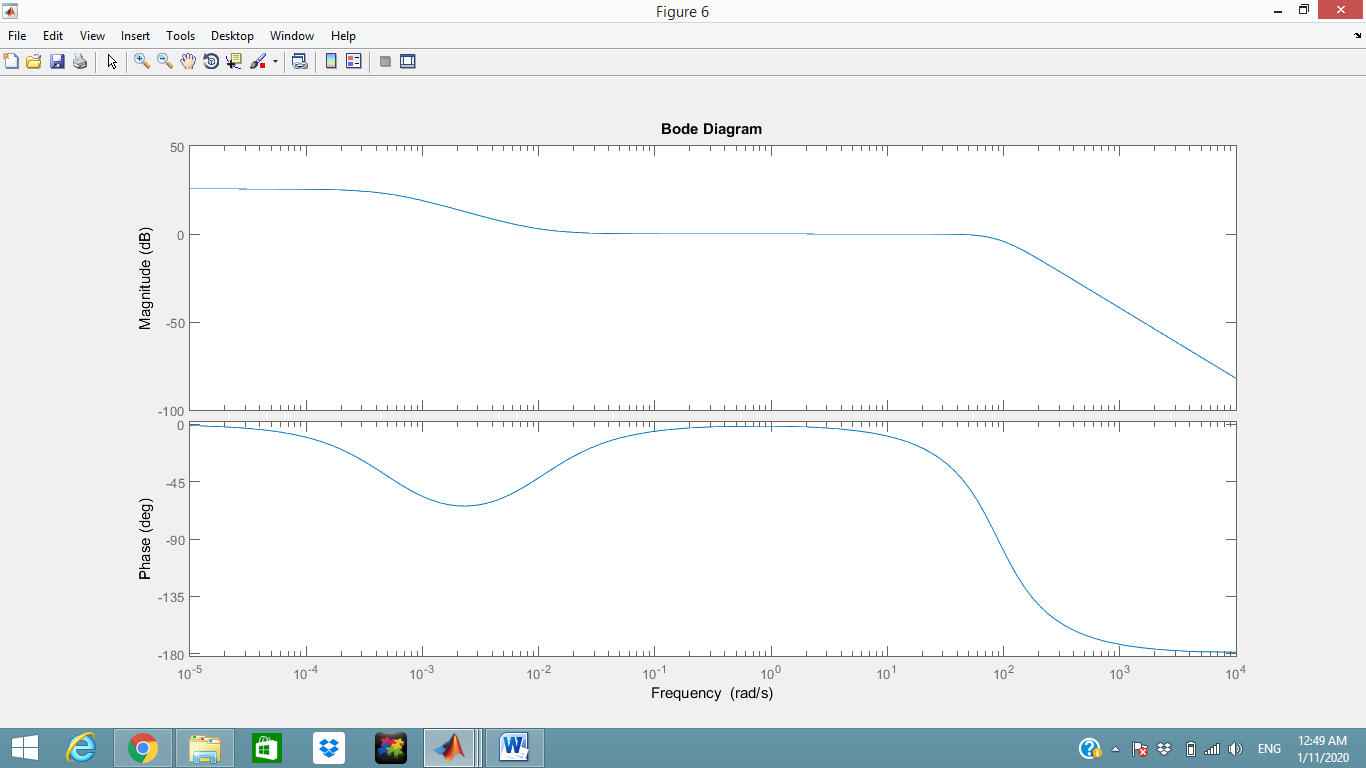












Lag compensator with tuning:

